

Dedicated to Prof. Ioan A. Rus on the occasion of his 85th anniversary

Implicit functional differential equations with linear modification of the argument, via weakly Picard operator theory

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ABSTRACT. Let $\mathbf{K} := \mathbf{R}$ or \mathbf{C} , $0 < \lambda < 1$ and $f \in C([0, b] \times \mathbf{K}^3, \mathbf{K})$.

In this paper we use the weakly Picard operator theory technique to study the following functional-differential equation

$$y'(x) = f(x, y(x), y'(x), y(\lambda x)), x \in [0, b].$$

1. INTRODUCTION

The theory of functional-differential equations and of functional-integral equations are both active fields in mathematics.

Many problems from physics, chemistry, astronomy, biology, engineering, social sciences lead to mathematical models described by functional-differential and functional-integral equations (see [7], [8], [10], [13], [15], [19], [21]). The theory of this kind of equations has developed very much.

For the monographs in this field we quote here [1]-[4], such as a large number of papers, which contain a lot of techniques, ideas and applications.

Let $\mathbf{K} := \mathbf{R}$ or \mathbf{C} , $0 < \lambda < 1$ and $f \in C([0, b] \times \mathbf{K}^3, \mathbf{K})$.

In this paper we use the weakly Picard operator theory technique to study the following functional differential equation

$$y'(x) = f(x, y(x), y'(x), y(\lambda x)), x \in [0, b].$$

We obtain existence, uniqueness and data dependence results for the solution.

2. PRELIMINARIES

2.1. Notations and terminology. Let X be a nonempty set and $A : X \rightarrow X$ an operator.

We denote by $A^0 := 1_X$, $A^1 := A$, ..., $A^{n+1} := A \circ A^n$, $n \in \mathbb{N}$, the iterate operators of A . Also:

$$\begin{aligned} P(X) & : = \{Y \subset X \mid Y \neq \emptyset\}, \\ I(A) & : = \{Y \in P(X) \mid A(Y) \subset Y\}, \end{aligned}$$

the family of all nonempty invariant subsets of A ,

$$F_A = \{x \in X \mid A(x) = x\},$$

the fixed point set of the operator A .

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Let (X, \rightarrow) be an L -space (see [14],[18]).

Following Rus I. A. ([11], [14], [15]), we have:

Definition 2.1. A is a Picard operator if there exists $x^* \in X$ such that

- 1) $F_A = \{x^*\}$;
- 2) the successive approximation sequence $(A^n(x_0))_{n \in \mathbb{N}}$ converges to x^* , for all $x_0 \in X$

Definition 2.2. A is a weakly Picard operator if the sequence $(A^n(x_0))_{n \in \mathbb{N}}$ converges for all $x_0 \in X$ and the limit (which generally depends on x_0) is a fixed point of A .

Definition 2.3. If $A : X \rightarrow X$ is a weakly Picard operator then we define the operator A^∞ as follows:

$$A^\infty : X \rightarrow X, \quad A^\infty(x) := \lim_{n \rightarrow \infty} A^n(x), \text{ for all } x \in X.$$

We remark that $A^\infty(X) = F_A$. So A^∞ is an retract of X on F_A .

2.2. Weakly Picard operators. We have the following theorems:

Theorem 2.1. (Contraction mapping principle). Let (X, d) be a complete metric space and $A : X \rightarrow X$ a contraction. Then A is a Picard operator.

Theorem 2.2. (Characterization theorem). Let (X, d) be a metric space and $A : X \rightarrow X$ an operator. The operator A is a weakly Picard operator if and only if there exists a partition of X , $X = \cup_{\lambda \in \Lambda} X_\lambda$, such that:

- (i) $X_\lambda \in I(A)$;
- (ii) $A|_{X_\lambda} : X_\lambda \rightarrow X_\lambda$ is a Picard operator, for all $\lambda \in \Lambda$.

Fibre generalized contraction theorem is a fixed point theorem for operators on cartesian product. This theorem is useful for proving solution of operatorial equations to be differentiable and it is a generalization of a result given by Hirsch and Pugh in [5]. See also [12], [20], [21].

Theorem 2.3. (Fibre contraction theorem). Let (X, d) be a metric space, (Y, ρ) be a complete metric space and $T : X \times Y \rightarrow X \times Y$. We suppose that:

- (i) $T(x, y) = (T_1(x), T_2(x, y))$, for all $x \in X, y \in Y$;
- (ii) $T_1 : X \rightarrow X$ is a weakly Picard operator;
- (iii) there exists $c \in]0, 1[$, such that

$$\rho(T_2(x, y_1), T_2(x, y_2)) \leq c\rho(y_1, y_2),$$

for all $x \in X, y_1, y_2 \in Y$.

Then the operator T is a weakly Picard operator. Moreover, if T_1 is a Picard operator, then T is a Picard operator.

We will use the previous result to study the differentiability with respect to parameter λ for the solution of our equation.

3. CAUCHY PROBLEM: EXISTENCE AND UNIQUENESS

Let $\mathbf{K} := \mathbf{R}$ or \mathbf{C} , $0 < \lambda < 1$ and $f \in C([0, b] \times \mathbf{K}^3, \mathbf{K})$.

We consider the following Cauchy problem:

$$(3.1) \quad y'(x) = f(x, y(x), y'(x), y(\lambda x)), x \in [0, b],$$

$$(3.2) \quad y(0) = y_0,$$

where $y_0 \in \mathbf{K}$.

The problem (3.1)+(3.2) is equivalent to the following:

$$(3.3) \quad \begin{cases} y'(x) = v(x) \\ v(x) = f\left(x, y_0 + \int_0^x v(s)ds, v(x), y_0 + \int_0^{\lambda x} v(s)ds\right) \\ y(0) = y_0, \end{cases}$$

or

$$(3.4) \quad \begin{cases} y(x) = y_0 + \int_0^x v(s)ds, \quad x \in [0, b] \\ v(x) = f\left(x, y_0 + \int_0^x v(s)ds, v(x), y_0 + \int_0^{\lambda x} v(s)ds\right), \\ x \in [0, b]. \end{cases}$$

Let $T : C([0, b], \mathbf{K}) \rightarrow C([0, b], \mathbf{K})$ be the operator defined by

$$(T(v))(x) := f\left(x, y_0 + \int_0^x v(s)ds, v(x), y_0 + \int_0^{\lambda x} v(s)ds\right).$$

So we obtain a fixed point problem

$$(3.5) \quad v(x) = (T(v))(x), \quad v \in C([0, b], \mathbf{K}).$$

The problem (3.1)+(3.2) has a unique solution if and only if the problem (3.5) has a unique solution, $v^* \in C([0, b], \mathbf{K})$.

Consequently, in our paper, we will study the fixed point problem (3.5).

By using Contraction principle we give an existence and uniqueness theorem.

Theorem 3.4. *We suppose that there exist $L_1 > 0, 0 < L_2 < 1, L_3 > 0$ such that*

$$|f(x, u_1, u_2, u_3) - f(x, u_4, u_5, u_6)| \leq L_1|u_1 - u_4| + L_2|u_2 - u_5| + L_3|u_3 - u_6|$$

for all $x \in [0, b]$ and all $u_k \in K, k = \overline{1, 6}$.

Then

(a) *the problem (3.5) has a unique solution $v^* \in C([0, b], K)$;*

(b) *for all $v_0 \in C([0, b], K)$ the sequence $(v_n)_{n \in \mathbb{N}}$ defined by*

$$v_{n+1}(x) := f\left(x, y_0 + \int_0^x v_n(s)ds, v_n(x), y_0 + \int_0^{\lambda x} v_n(s)ds\right),$$

converges uniformly to v^* on $[0, b]$.

Proof. Let $\|\cdot\|_B$ be a Bielecki norm on $C([0, b], \mathbf{K})$ defined by

$$\|v\|_B = \max_{x \in [0, b]} |v(x)|e^{-\tau x}, \quad \text{where } \tau > 0.$$

Consider the above operator $T : (C([0, b], \mathbf{K}), \|\cdot\|_B) \rightarrow (C([0, b], \mathbf{K}), \|\cdot\|_B)$.

We have

$$\begin{aligned} |(T(v))(x) - (T(w))(x)| &\leq L_1 \int_0^x |v(s) - w(s)|ds + \\ &+ L_2 |v(x) - w(x)| + L_3 \int_0^{\lambda x} |v(s) - w(s)|ds \leq \end{aligned}$$

$$\begin{aligned} &\leq L_1 \int_0^x |v(s) - w(s)| e^{-\tau s} e^{\tau s} ds + L_2 |v(x) - w(x)| e^{-\tau x} e^{\tau x} + \\ &+ L_3 \int_0^x |v(s) - w(s)| e^{-\tau s} e^{\tau s} ds \leq \frac{L_1 + L_3}{\tau} (e^{\tau x} - 1) \|v - w\|_B + \\ &+ L_2 \|v - w\|_B e^{\tau x} \leq \left(\frac{L_1 + L_3}{\tau} + L_2 \right) \|v - w\|_B e^{\tau x}, \end{aligned}$$

for all $x \in [0, b]$.

Therefore,

$$|(T(v))(x) - (T(w))(x)| e^{-\tau x} \leq \left(\frac{L_1 + L_3}{\tau} + L_2 \right) \|v - w\|_B,$$

for all $x \in [0, b]$.

This implies that

$$\|T(v) - T(w)\|_B \leq \left(\frac{L_1 + L_3}{\tau} + L_2 \right) \|v - w\|_B,$$

for all $v, w \in C([0, b], \mathbf{K})$.

We can choose τ large enough such that $\frac{L_1 + L_3}{\tau} + L_2 < 1$.

By applying Contraction principle we obtain (a) and (b). \square

Remark 3.1. Let us consider the operator

$$A : C([0, b], \mathbf{K}) \times C([0, b], \mathbf{K}) \rightarrow C([0, b], \mathbf{K}) \times C([0, b], \mathbf{K})$$

defined by

$$A(y, v)(x) := \left(y(0) + \int_0^x v(s) ds, f \left(x, y(0) + \int_0^x v(s) ds, v(x), y(0) + \int_0^{\lambda x} v(s) ds \right) \right).$$

From the Theorem 3.4. it is clear that the operator A , in the conditions of Theorem 3.4., is a weakly Picard operator. Indeed, let for $y_0 \in \mathbf{K}$

$$X_{y_0} := \{y \in C([0, b], \mathbf{K}) \mid y(0) = y_0\}.$$

Then

$$C([0, b], \mathbf{K}) \times C([0, b], \mathbf{K}) = \bigcup_{y_0 \in \mathbf{K}} (X_{y_0} \times C([0, b], \mathbf{K}))$$

is an invariant partition of $C([0, b], \mathbf{K}) \times C([0, b], \mathbf{K})$, i.e.,

$$A(X_{y_0} \times C([0, b], \mathbf{K})) \subset X_{y_0} \times C([0, b], \mathbf{K}), \text{ for all } y_0 \in \mathbf{K}.$$

From a similar proof as in Theorem 3.4. we have that $A|_{X_{y_0} \times C([0, b], \mathbf{K})}$ is a Picard operator for each $y_0 \in \mathbf{K}$. So, from Theorem 2.2., the operator A is a weakly Picard operator.

From the definition of operator A we have that:

- if y is a solution of the equation 3.1., then $(y, y') \in F_A$;
- if $(y, v) \in F_A$, then y is a solution of (3.1).

4. DATA DEPENDENCE

By using Fibre contraction theorem we give a data dependence theorem for the solution of the following equation:

$$(4.6) \quad v(x, \lambda) = (T(v))(x, \lambda), \quad v \in C([0, b] \times]0, 1[, \mathbf{K}).$$

We have

Theorem 4.5. *We suppose that:*

- (i) $f(x, \cdot, \cdot, \cdot) \in C^1(\mathbf{K}^3)$, for all $x \in [0, b]$;
- (ii) there exist $M_k > 0$, $k = \overline{1, 3}$, such that

$$\left| \frac{\partial f}{\partial u_k}(x, u_1, u_2, u_3) \right| \leq M_k, \quad k = \overline{1, 3},$$

for all $x \in [0, b]$ and all $u_k \in \mathbf{K}$, $k = \overline{1, 3}$;

- (iii) $0 < M_2 < 1$.

Then

- (a) the equation (4.6) has a unique solution $v^* \in C([0, b] \times]0, 1[, \mathbf{K})$;
- (b) for all $v_0 \in C([0, b] \times]0, 1[, \mathbf{K})$ the sequence $(v_n)_{n \in \mathbb{N}}$ defined by

$$v_{n+1}(x, \lambda) := f \left(x, y_0 + \int_0^x v_n(s, \lambda) ds, v_n(x, \lambda), y_0 + \int_0^{\lambda x} v_n(s, \lambda) ds \right)$$

converges uniformly to v^* on each compact of $[0, b] \times]0, 1[$;

- (c) the sequence $(w_n)_{n \in \mathbb{N}}$ defined by

$$\begin{aligned} w_{n+1}(x, \lambda) &:= \\ &= \frac{\partial f}{\partial u_1} \left(x, y_0 + \int_0^x v_n(s, \lambda) ds, v_n(x, \lambda), y_0 + \int_0^{\lambda x} v_n(s, \lambda) ds \right) \int_0^x w_n(s, \lambda) ds + \\ &+ \frac{\partial f}{\partial u_2} \left(x, y_0 + \int_0^x v_n(s, \lambda) ds, v_n(x, \lambda), y_0 + \int_0^{\lambda x} v_n(s, \lambda) ds \right) w_n(x, \lambda) + \\ &+ \frac{\partial f}{\partial u_3} \left(x, y_0 + \int_0^x v_n(s, \lambda) ds, v_n(x, \lambda), y_0 + \int_0^{\lambda x} v_n(s, \lambda) ds \right) \cdot \\ &\cdot \left(\int_0^{\lambda x} w_n(s, \lambda) ds + x v_n(\lambda x, \lambda) \right), \end{aligned}$$

where $w_0 = \frac{\partial v_0}{\partial \lambda}$, converges uniformly to $\frac{\partial v^*}{\partial \lambda}$ on each compact of $[0, b] \times]0, 1[$.

Proof. For $0 < \lambda_1 < \lambda_2 < 1$, we denote $X = (C([0, b] \times [\lambda_1, \lambda_2], \mathbf{K}), \|\cdot\|_\tau)$, where

$$\|v\|_\tau = \max_{\substack{x \in [0, b] \\ \lambda \in [\lambda_1, \lambda_2]}} |v(x, \lambda)| e^{-\tau x},$$

and $\tau > 0$.

Consider the operator $S_1 : X \rightarrow X$, defined by

$$(S_1(v))(x, \lambda) := f \left(x, y_0 + \int_0^x v(s, \lambda) ds, v(x, \lambda), y_0 + \int_0^{\lambda x} v(s, \lambda) ds \right).$$

The operator S_1 is a Lipchitz operator with the constant

$$L_{S_1} = \frac{M_1 + M_3}{\tau} + M_2.$$

Because of condition (iii), and by choosing τ large enough we have that $L_{S_1} < 1$.

By applying Contraction principle to the operator S_1 we obtain (a) and (b).

Let us prove that there exists $\frac{\partial v^*}{\partial \lambda}$ and

$$\frac{\partial v^*}{\partial \lambda}(x, \cdot) \in C([\lambda_1, \lambda_2], \mathbf{K}), \text{ for all } x \in [0, b].$$

We have

$$(4.7) \quad v^*(x, \lambda) = f \left(x, y_0 + \int_0^x v^*(s, \lambda) ds, v^*(x, \lambda), y_0 + \int_0^{\lambda x} v^*(s, \lambda) ds \right).$$

If we suppose that there exists $\frac{\partial v^*}{\partial \lambda}$, then from (4.7) we obtain

$$\begin{aligned} \frac{\partial v^*}{\partial \lambda}(x, \lambda) &= \frac{\partial f}{\partial u_1} \left(x, y_0 + \int_0^x v^*(s, \lambda) ds, v^*(x, \lambda), y_0 + \int_0^{\lambda x} v^*(s, \lambda) ds \right) \int_0^x \frac{\partial v^*}{\partial \lambda}(s, \lambda) ds + \\ &+ \frac{\partial f}{\partial u_2} \left(x, y_0 + \int_0^x v^*(s, \lambda) ds, v^*(x, \lambda), y_0 + \int_0^{\lambda x} v^*(s, \lambda) ds \right) \frac{\partial v^*}{\partial \lambda}(x, \lambda) + \\ &+ \frac{\partial f}{\partial u_3} \left(x, y_0 + \int_0^x v^*(s, \lambda) ds, v^*(x, \lambda), y_0 + \int_0^{\lambda x} v^*(s, \lambda) ds \right) \cdot \\ &\cdot \left(\int_0^{\lambda x} \frac{\partial v^*}{\partial \lambda}(s, \lambda) ds + xv^*(\lambda x, \lambda) \right). \end{aligned}$$

The previous relationship suggests us to consider the operator $S_2 : X \times X \rightarrow X$, defined by

$$\begin{aligned} (S_2(v, y))(x, \lambda) &:= \\ &= \frac{\partial f}{\partial u_1} \left(x, y_0 + \int_0^x v(s, \lambda) ds, v(x, \lambda), y_0 + \int_0^{\lambda x} v(s, \lambda) ds \right) \int_0^x y(s, \lambda) ds + \\ &+ \frac{\partial f}{\partial u_2} \left(x, y_0 + \int_0^x v(s, \lambda) ds, v(x, \lambda), y_0 + \int_0^{\lambda x} v(s, \lambda) ds \right) y(x, \lambda) + \\ &+ \frac{\partial f}{\partial u_3} \left(x, y_0 + \int_0^x v(s, \lambda) ds, v(x, \lambda), y_0 + \int_0^{\lambda x} v(s, \lambda) ds \right) \cdot \\ &\cdot \left(\int_0^{\lambda x} y(s, \lambda) ds + xv(\lambda x, \lambda) \right). \end{aligned}$$

By using (i) and(ii) we obtain that

$$\|S_2(v, y_1) - S_2(v, y_2)\|_{\tau} \leq \left(\frac{M_1 + M_3}{\tau} + M_2 \right) \|y_1 - y_2\|_{\tau},$$

for all $y_1, y_2 \in X$.

Because of condition (iii), and by choosing τ large enough, we have that S_2 is a contraction with respect to the second argument.

If we take the operator $S : X \times X \rightarrow X \times X$, $S = (S_1, S_2)$ then we are in the conditions of Fibre contraction theorem. Let (v^*, w^*) the unique fixed point of the operator S .

If we take $v_0 = 0, w_0 = 0$ then $w_1 = \frac{\partial v_1}{\partial \lambda}$.

By mathematical induction method we can prove that $w_n = \frac{\partial v_n}{\partial \lambda}$.

Thus $(v_n)_{n \in \mathbb{N}}$ converges uniformly to v^* and $\left(\frac{\partial v_n}{\partial \lambda}\right)_{n \in \mathbb{N}^*}$ converges uniformly to w^* .

By using a Weiestrass argument we obtain that $\frac{\partial v^*}{\partial \lambda}$ exists and $\frac{\partial v^*}{\partial \lambda} = w^*$, and w^* is a continuous function.

So, we have (c). □

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