# Approximation of solutions of Hammerstein equations with monotone mappings in real Banach spaces 

C. E. Chidume, A. Adamu and L. C. Okereke


#### Abstract

Let $E$ be a uniformly convex and uniformly smooth real Banach space with dual space, $E^{*}$. Let $F: E \rightarrow E^{*}, K: E^{*} \rightarrow E$ be maximal monotone mappings. An iterative algorithm is constructed and the sequence of the algorithm is proved to converge strongly to a solution of the Hammerstein equation $u+K F u=0$. This theorem is a significant improvement of some important recent results which were proved in $L_{p}$ spaces, $1<p \leq 2$ under the assumption that $F$ and $K$ are bounded. This restriction on $K$ and $F$ have been dispensed with even in the more general setting considered here. Finally, a numerical experiment is presented to illustrate the convergence of the sequence of the algorithm which is found to be much faster, in terms of the number of iterations and the computational time than the convergence obtained with existing algorithms.


## 1. Introduction

Let $E$ be a real Banach space with a strictly convex dual space, $E^{*}$. Consider on $E$ the Hammerstein equation

$$
\begin{equation*}
(I+K F) u=0, \tag{1.1}
\end{equation*}
$$

where, $F: E \rightarrow E^{*}$ is a nonlinear mapping and $K: E^{*} \rightarrow E$ is a linear map, such that $R(F) \subset D(K)$. If $\Omega$ denotes a domain of $\sigma$-finite measure $d y$ in $R^{N}$, and $\kappa: \Omega \times \Omega \rightarrow \mathbb{R}$ and $f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are measurable real-valued functions on $\Omega$, one can define a linear integral operator $K$ by $K v:=\int_{\Omega} \kappa(\cdot, y) v(y) d y$ and an operator $F$ by the Nemitskyi or superposition operator given by $F u:=f(\cdot, u(\cdot))$ to obtain equation (1.1).

Numerous problems in differential equation, optimal control, automation and network systems can, as a rule, be modeled as a Hammerstein equation (see, e.g., Pascali and Sburlan [35]).

Several existence and uniqueness theorems have been proved for equations of Hammerstein type (see, e.g., Brezis and Browder [4, 5], Browder and Gupta [7], Chepanovich [8], De Figueiredo and Gupta [24]).

Let $A: D(A) \subset E \rightarrow E$ be a mapping. $A$ is called accretive if for each $u, v \in D(A)$, there exists $j(u-v) \in J(u-v)$ such that $\langle A u-A v, j(u-v)\rangle \geq 0$, where $J: E \rightarrow 2^{E^{*}}$ is the normalized duality map defined, for each $x \in E$, by $J(x)=\left\{x^{*} \in E^{*}:\left\langle x, x^{*}\right\rangle=\right.$ $\left.\|x\|\left\|x^{*}\right\|,\left\|x^{*}\right\|=\|x\|\right\}$. The map $A$ is called $m$-accretive if, it is accretive and, in addition, the graph of $A$ is not properly contained in the graph of any other accretive mapping. In Hilbert spaces, accretive mappings are called monotone. The accretive mappings were

[^0]introduced independently in 1967 by Browder [3] and Kato [30]. Interest in such mappings stems mainly from their firm connection with evolution equations (see e.g., Berinde [2], Chidume [9], Gobel and Reich [27] and the references contained in them).

A mapping $B: D(B) \subset E \rightarrow E^{*}$ is called monotone if for all $x, y \in E,\langle B x-B y, x-y\rangle \geq$ 0 . The map $B$ is called maximal monotone if, in addition, $R(J+\lambda B)$ is $E^{*}$, for all $\lambda>0$. Monotone mappings were studied in Hilbert spaces by Zarantonello [41], Minty [32], and a host of other authors. Interest in such mappings stems from their usefulness in applications, (in particular, monotone mappings are useful in convex optimization problems see, e.g., Chidume and Bello [19]).

In general, equations of Hammerstein type are nonlinear and thus, there is no closed form solutions of such equations. Consequently, methods for approximating such equations are of interest. Several attempts have been made to approximate solutions of equations of Hammerstein type.

An early method was that used by Brezis and Browder [6] in a special case where one of the operators is angle bounded (see e.g., Pascali and Sburlan, [35]). They proved strong convergence of a suitable defined Galerking approximation to a solution of (1.1), (see e.g., Brezis and Browder [6]).

The first iterative methods for approximating solutions of Hammerstein equations, in real Banach spaces more general than Hilbert spaces, as far as we know, were obtained by Chidume and Zegeye [14] (see also Chidume [9], Chapter 13).

Let $X$ be a real Banach space and $F, K: X \rightarrow X$ be accretive-type mappings. Let $E:=X \times X$. Then, defined $T: E \rightarrow E$ by $T[u, v]=[F u-v, K v+u]$, for $[u, v] \in E$. We note that $T[u, v]=0 \Leftrightarrow u$ solves (1.1) and $v=F u$. With this, they were able to obtain strong convergence of an iterative algorithm defined in the cartesian product space $E$ to a solution of the Hammerstein equation (1.1). Extensions of these early results of Chidume and Zegeye [14] were obtained by several authors (see, e.g., Chidume and Zegeye [13, 15], Chidume and Djitte [21, 22], Chidume and Ofoedu [12], Chidume and Shehu [10, 11, 20], Zegeye and Molanza [42], Shehu [37], Minjibir and Mohammed [33] and the references contained in them).

In 2013, Djitte and Sene [26] proved strong convergence theorem for the following explicit iterative algorithm in uniformly smooth real Banach spaces.

Theorem 1.1. Let $E$ be a uniformly smooth real Banach space and $K, F: E \rightarrow E$ be bounded and accretive mappings with $R(F)=D(K)=E$. Let $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ be sequences in $E$ defined iteratively from arbitrary points $u_{1}, v_{1} \in E$ as follows:

$$
\left\{\begin{array}{l}
\left.u_{n+1}=u_{n}-\lambda^{2}\left(F u_{n}-v_{n}\right)-\lambda_{n} \theta_{n}\left(u_{n}-u_{1}\right)\right)  \tag{1.2}\\
\left.v_{n+1}=v_{n}-\lambda_{n}^{2}\left(K v_{n}+u_{n}\right)-\lambda_{n} \theta_{n}\left(v_{n}-v_{1}\right)\right)
\end{array}\right.
$$

where $\left\{\lambda_{n}\right\}$ and $\left\{\theta_{n}\right\}$ are real sequences in $(0,1)$ satisfying some appropriate conditions. Suppose that $u+K F u=0$ has a solution $u^{*}$, then the sequence $\left\{u_{n}\right\}$ converges to $u^{*}$.

In 2016, Chidume and Idu [16], proved strong convergence theorem for the following explicit iterative algorithm in uniformly convex uniformly smooth real Banach spaces.

Theorem 1.2. Let $E$ be a uniformly convex and uniformly smooth real Banach space and $F$ : $E \rightarrow E^{*}, K: E^{*} \rightarrow E$ be maximal monotone and bounded maps, respectively. For arbitrary $(u, v) \in E \times E^{*}$, define the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ in $E$ and $E^{*}$, respectively, by

$$
\left\{\begin{array}{l}
u_{n+1}=J^{-1}\left(J u_{n}-\lambda_{n}\left(F u_{n}-v_{n}\right)-\lambda_{n} \theta_{n}\left(J u_{n}-J u\right)\right), n \geq 1  \tag{1.3}\\
v_{n+1}=J\left(J^{-1} v_{n}-\lambda_{n}\left(K v_{n}+u_{n}\right)-\lambda_{n} \theta_{n}\left(J^{-1} v_{n}-J^{-1} v\right)\right), n \geq 1
\end{array}\right.
$$

Assume that the equation $u+K F u=0$ has a solution. Then, the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ converge strongly to $u^{*}$ and $v^{*}$, respectively, where $u^{*}$ is a solution of (1.1) with $v^{*}=F u^{*}$.

Recently, Uba et al. [40], introduced a new coupled iterative algorithm and proved the following strong convergence theorem.

Theorem 1.3. Let $E=L_{p}, 1<p \leq 2$. Let $F: E \rightarrow E^{*}$ and $K: E^{*} \rightarrow E$ be monotone and bounded maps. For $\left(u_{0}, v_{0}\right) \in E \times E^{*}$, define the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ in $E$ and $E^{*}$, respectively by

$$
\left\{\begin{array}{l}
u_{n+1}=J^{-1}\left(J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right), n \geq 0,  \tag{1.4}\\
v_{n+1}=J\left(J^{-1} v_{n}-\alpha_{n}\left(K v_{n}+u_{n}\right)-\alpha_{n} \theta_{n} J^{-1} v_{n}\right), n \geq 0,
\end{array}\right.
$$

where $\left\{\alpha_{n}\right\}$ and $\theta_{n}$ are acceptably paired sequences in $(0,1)$. Assume that the equation $u+K F u=$ 0 has a solution. Then, the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ converge strongly to $u^{*}$ and $v^{*}$, respectively, where $u^{*}$ is the solution of $u+K F u=0$ with $v^{*}=F u^{*}$.

It is our purpose in this paper to prove a significant improvement of Theorem 1.3. We extend Theorem 1.3 to uniformly convex and uniformly smooth real Banach spaces and, at the same time, dispense with the requirement in Theorem 1.3 that the mappings $K$ and $F$ be bounded. In particular, our Theorem is applicable in $L_{p}$ spaces, $1<p<\infty$, thereby providing an iterative algorithm which converges strongly to a solution of the Hammerstein equation (1.1) in $L_{p}$ spaces, $1<p<\infty$, and without requiring that $F$ and $K$ be bounded, as is imposed in Theorem 1.3. Furthermore, our theorem improves and compliments Theorems 1.2 and 1.1 see Remark 4.5 below.

## 2. Preliminaries

In this section, we present definitions of some terms, and results that will be needed in the proof of our main theorem.

Definition 2.1. Let $E$ be a smooth real Banach space. The Lyapounov functional $\phi: E \times$ $E \rightarrow \mathbb{R}$ is defined by

$$
\begin{equation*}
\phi(u, v)=\|u\|^{2}-2\langle u, J v\rangle+\|v\|^{2}, \forall u, v \in E . \tag{2.5}
\end{equation*}
$$

It was introduced by Alber and has been studied by many authors (see, e.g., Alber [1]; Chidume et al. [17, 18]; Kamimura and Takahashi [29]; Nilsrakoo and Saejung [34]; and the references contained in them). It is easy to see that from the definition of $\phi$,

$$
\begin{equation*}
(\|u\|-\|v\|)^{2} \leq \phi(u, v) \leq(\|u\|+\|v\|)^{2}, \forall u, v \in E . \tag{2.6}
\end{equation*}
$$

Definition 2.2. Let $E$ be a normed linear space, consider the map $W: E \times E^{*} \rightarrow \mathbb{R}$ defined by $W\left(u, u^{*}\right)=\|u\|^{2}-2\left\langle u, u^{*}\right\rangle+\left\|u^{*}\right\|, \forall u \in E, u^{*} \in E^{*}$. Observe that $W\left(u, u^{*}\right)=$ $\phi\left(u, J^{-1} u^{*}\right), \forall u \in E, u^{*} \in E^{*}$.

Lemma 2.1 (Alber and Ryazantseva, [1]). Let $E$ be a reflexive strictly convex and smooth Banach space with $E^{*}$ as its dual. Then, for each $u \in E$ and $u^{*}, v^{*} \in E^{*}$, we have

$$
\begin{equation*}
W\left(u, u^{*}\right)+2\left\langle J^{-1} u^{*}-u, v^{*}\right\rangle \leq W\left(u, u^{*}+v^{*}\right) . \tag{2.7}
\end{equation*}
$$

Lemma 2.2 (Alber and Ryazantseva, [1]). Let $E$ be a reflexive strictly convex and smooth Banach space with dual space $E^{*}$. Let $V: E \times E \rightarrow \mathbb{R}$ be defined by $V(u, v)=\frac{1}{2} \phi(v, u)$. Then, $\forall u, v, s \in E$,

$$
V(u, v)-V(s, u) \geq\langle s-v, J u-J s\rangle, \text { i.e., } \phi(v, u)-\phi(u, s) \geq 2\langle s-v, J u-J s\rangle,
$$

and also, $V(u, v) \leq\langle u-v, J u-J v\rangle$.

Lemma 2.3 (Chidume and Idu, [16]). Let $E$ be a smooth real Banach space with dual space $E^{*}$. Let $\phi: E \times E \rightarrow \mathbb{R}$ be the Lyapounov functional. Then, $\phi(v, u)=\phi(u, v)-\langle u+v, J u-J v\rangle+$ $2\left(\|u\|^{2}-\|v\|^{2}\right), \forall u, v \in E$.
Lemma 2.4 (Alber and Ryazantseva, [1]). Let E be a uniformly convex Banach space. Then, for any $r>0$ and any $u, v \in E$ such that $\|u\| \leq r,\|v\| \leq r$, the following inequality holds: $\langle u-v, J u-J v\rangle \geq(2 L)^{-1} \delta_{E}\left(c_{2}^{-1}\|u-v\|\right)$, where $c_{2}=2 \max \{1, r\}, 1<L<1.7$. Define

$$
\begin{equation*}
D:=4 r L \sup \{\|J u-J v\|:\|x\| \leq r,\|y\| \leq r\}+1 \tag{2.8}
\end{equation*}
$$

Lemma 2.5 (Alber and Ryazantseva, [1]). Let E be a uniformly convex Banach space. Then, for any $r>0$ and any $u, v \in E$ such that $\|u\| \leq r,\|v\| \leq r$, the following inequality holds: $\langle u-v, J u-J v\rangle \geq(2 L)^{-1} \delta_{E^{*}}\left(c_{2}^{-1}\|J u-J v\|\right)$, where $c_{2}=2 \max \{1, r\}, 1<L<1.7$.

Lemma 2.6 (Rockafellar, [39]; see also, Pascali and Sburlan, [35]). A monotone mapping $T: E \rightarrow 2^{E^{*}}$ is locally bounded at the interior points of its domain.
Lemma 2.7 (Reich, [36]). Let $E^{*}$ be a real strictly convex dual space with a Fréchet differentiable norm, and let $A$ be a maximal monotone operator from $E$ to $E^{*}$ such that $A^{-1} 0 \neq \emptyset$. Let $s \in E^{*}$ be arbitrary but fixed. For each $\rho>0$ there exists a unique $u_{\rho} \in E$ such that $J u_{\rho}+\rho A u_{\rho} \ni s$. Furthermore, $u_{\rho}$ converges strongly to a unique point $p \in A^{-1} 0$.
Corollary 2.1. From Lemma 2.7, setting $\rho_{n}:=\frac{1}{\theta_{n}}$, where $\theta_{n} \rightarrow 0$ as $n \rightarrow \infty, z=j(v)$ for some $j(v) \in J(v), v \in E, y_{n}:=\left(j+\frac{1}{\theta_{n}} A\right)^{-1} z$, we obtain: $A y_{n}=\theta_{n}\left(j(v)-j\left(y_{n}\right)\right)$, for some $j\left(y_{n}\right) \in$ $J\left(y_{n}\right)$. Furthermore, $y_{n} \rightarrow y^{*} \in A^{-1} 0$, where $A: E \rightarrow E^{*}$ is maximal monotone (see, Chidume and Idu, [16]).

Remark 2.1. Let $r>0$ such that $\|v\| \leq r,\left\|y_{n}\right\| \leq r$, for all $n \geq 1$. The following estimates will be needed in the sequel.

$$
\begin{gather*}
\left\|y_{n-1}-y_{n}\right\| \leq c_{2} \delta_{E}^{-1}\left(\frac{\theta_{n-1}-\theta_{n}}{\theta_{n}} D\right)  \tag{2.9}\\
\left\|J y_{n-1}-J y_{n}\right\| \leq c_{2} \delta_{E^{*}}^{-1}\left(\frac{\theta_{n-1}-\theta_{n}}{\theta_{n}} D\right) \tag{2.10}
\end{gather*}
$$

where $D$ is the constant defined in equation (2.8) and $\delta_{E}$ denotes the modulus of convexity of a normed space $E$ (see, e.g., Lindenstrauss and Tzafriri [31], Chidume [9]), $\left\{y_{n}\right\}$ and $\left\{\theta_{n}\right\}$ are as defined in Corollary 2.1 (see, Chidume and Idu, [16], Remark 1).
Lemma 2.8 (Kamimura and Takahashi, [29]). Let E be a uniformly convex and smooth real Banach space, and let $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ be two sequences of $E$. If either $\left\{u_{n}\right\}$ or $\left\{v_{n}\right\}$ is bounded and $\phi\left(u_{n}, v_{n}\right) \rightarrow 0$ then $\left\|u_{n}-v_{n}\right\| \rightarrow 0$.
Lemma 2.9 ( $\mathrm{Xu},[38])$. Let $\left\{a_{n}\right\}$ be a sequence of non-negative real numbers satisfying the following relation:

$$
\begin{equation*}
a_{n+1} \leq\left(1-\sigma_{n}\right) a_{n}+\sigma_{n} b_{n}+c_{n}, n \geq 1, \tag{2.11}
\end{equation*}
$$

where $\left\{\sigma_{n}\right\},\left\{b_{n}\right\}$ and $\left\{c_{n}\right\}$ satisfy the conditions:
(i) $\left\{\sigma_{n}\right\} \subset[0,1], \sum_{n=1}^{\infty} \sigma_{n}=\infty ;$
(ii) $\limsup _{n \rightarrow \infty} b_{n} \leq 0 ;$
(iii) $c_{n} \geq 0, \sum_{n=1}^{\infty} c_{n}<\infty$.

Then, $\lim _{n \rightarrow \infty} a_{n}=0$.
Lemma 2.10 (Chidume and Idu, [16]). Let $X, Y$ be real uniformly convex and uniformly smooth spaces. Then $E=X \times Y$ is uniformly convex and uniformly smooth.

Lemma 2.11 (Chidume and Idu, [16]). Let $E$ be a uniformly convex and uniformly smooth real Banach Banach space and $F: E \rightarrow E^{*}, K: E^{*} \rightarrow E$ be maximal monotone. Define $A: E \times E^{*} \rightarrow E^{*} \times E$ by $A[u, v]=[F u-v, K v+u], \forall[u, v] \in E \times E^{*}$. Then, $A$ is maximal monotone.
Remark 2.2. The following estimates (see, Uba et al. [40], Remark 2) will be needed in the sequel.

$$
\begin{gather*}
J y_{n}+\frac{1}{\theta_{n}}\left(F y_{n}-y_{n}^{*}\right)=0, \forall n \geq 1, \text { and }  \tag{2.12}\\
J_{*} y_{n}^{*}+\frac{1}{\theta_{n}}\left(K y_{n}^{*}+y_{n}\right)=0, \forall n \geq 1, \tag{2.13}
\end{gather*}
$$

Remark 2.3. Let $y_{n} \rightarrow u^{*}$ and $y_{n}^{*} \rightarrow v^{*}$. From Lemma 2.7 we have that $\left[y_{n}, y_{n}^{*}\right]$ converges to a point in $A^{-1} 0$. This implies that $\left[u^{*}, v^{*}\right] \in A^{-1} 0$. Consequently, $A\left[u^{*}, v^{*}\right]=0$, that is $F u^{*}-v^{*}=0$ and $K v^{*}+u^{*}=0$. Hence, $v^{*}=F u^{*}$ and $u^{*}+K F u^{*}=0$.
Definition 2.3. If $A: E \rightarrow 2^{E^{*}}$ is monotone with $0 \in \operatorname{Int} D(A)$, then $A$ is quasi-bounded, i.e., if for any $M>0$ there exists $C>0$ such that $(y, v) \in G(A),\langle y, v\rangle \leq M\|y\|$ and $\|y\| \leq M$ implies $\|v\| \leq C$ (see I. Cioranescu [23], p. 176).
Lemma 2.12. Let $E$ be a real normed space with dual space $E^{*}$. Any monotone map $A: D(A) \subset$ $E \rightarrow E^{*}$ with $0 \in \operatorname{Int} D(A)$ is quasi-bounded.

## 3. MAIN RESULT

In Theorem 3.4 below, the sequences $\left\{\alpha_{n}\right\}$ and $\left\{\theta_{n}\right\}$ are in $(0,1)$ and are assumed to satisfy the following conditions:
(i) $\delta_{E}^{-1}\left(\alpha_{n} M_{0}\right) \leq \theta_{n} \gamma_{0} ; \alpha_{n} M_{1} \leq \theta_{n} \gamma_{0}$,
(ii) $\delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right) \leq \theta_{n} \gamma_{0} ; \alpha_{n} M_{1}^{*} \leq \theta_{n} \gamma_{0}$,
for all $n \geq 1$ and for some constants, $M_{0}, M_{0}^{*}, M_{1}, M_{1}^{*}, \gamma_{0}>0$.
Theorem 3.4. Let $E$ be a uniformly convex and uniformly smooth real Banach space. Let $F$ : $E \rightarrow E^{*}, K: E^{*} \rightarrow E$ be maximal monotone mappings. For $u_{1} \in E, v_{1} \in E^{*}$, define the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ in $E$ and $E^{*}$, respectively by

$$
\begin{align*}
& u_{n+1}=J^{-1}\left(J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right)  \tag{3.14}\\
& v_{n+1}=J\left(J^{-1} v_{n}-\alpha_{n}\left(K v_{n}+u_{n}\right)-\alpha_{n} \theta_{n} J^{-1} v_{n}\right) . \tag{3.15}
\end{align*}
$$

Assume that the equation $u+K F u=0$ has a solution $u^{*}$, with $v^{*}=F u^{*}$. Then, the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ are bounded.
Proof. To show that the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ are bounded, set $w_{n}=\left(u_{n}, v_{n}\right), w^{*}=$ $\left(u^{*}, v^{*}\right) \in W=E \times E^{*}$, where $u^{*}$ is a solution (1.1) with $v^{*}=F u^{*}$. Define $\Phi: W \times W \rightarrow \mathbb{R}$ by $\Phi\left(w_{1}, w_{2}\right)=\phi\left(u_{1}, u_{2}\right)+\phi\left(v_{1}, v_{2}\right)$, where $w_{1}=\left(u_{1}, v_{1}\right)$ and $w_{2}=\left(u_{2}, v_{2}\right)$. Let $W$ be endowed with norm $\|(u, v)\|_{W}=\left(\|u\|_{E}^{2}+\|v\|_{E^{*}}^{2}\right)^{\frac{1}{2}}$. It suffices to show that $\left\{w_{n}\right\}$ is bounded. We show this by induction. Let $w_{1} \in W$. Then there exists $r>0$ such that $\left\|w^{*}\right\|_{W} \leq \frac{r}{4}$ and $\Phi\left(w^{*}, w_{1}\right) \leq \frac{r}{4}$. Let $B:=\left\{w=(u, v) \in W: \Phi\left(w^{*}, w\right) \leq r\right\}$. It suffices to show that $\Phi\left(w^{*}, w_{n}\right) \leq r$, for all $n \geq 1$. Let $w \in B$ and $\theta \in(0,1)$. Then, $\Phi\left(w^{*}, w\right) \leq$ $r \quad$ i.e., $\quad \phi\left(u^{*}, u\right)+\phi\left(v^{*}, v\right) \leq r$.Therefore, $\phi\left(u^{*}, u\right) \leq r$ and $\phi\left(v^{*}, v\right) \leq r$. Now, using inequality (2.6), $\phi\left(u^{*}, u\right) \leq r \Rightarrow\|u\| \leq\left\|u^{*}\right\|+\sqrt{r}$. Since $F$ is also locally bounded at $u$, there exists $k_{1}>0$ such that $\langle u, F u\rangle \leq k_{1}\|u\|$. Define $\sigma:=\max \left\{k_{1},\left\|u^{*}\right\|+\sqrt{r}\right\}$. Hence, $\langle u, F u\rangle \leq \sigma\|u\|$ and $\|u\| \leq \sigma$. By Lemma 2.12, $F$ is quasi-bounded. Thus, there
exists $\tau_{1}>0$ such that $\|F u\| \leq \tau_{1}, \forall(u, v) \in B$. Similarly, there exists $\tau_{2}>0$ such that $\|K v\| \leq \tau_{2}, \forall(u, v) \in B$. Define:

$$
\begin{array}{ll}
M_{1}=\sup \{\|F u-v+\theta J u\|\}+1 ; & M_{2}=\sup \left\{\left\|u-u^{*}\right\|\right\}+1 \\
M_{1}^{*}=\sup \left\{\left\|K v+u+\theta J^{-1} v\right\|\right\}+1 ; & M_{2}^{*}=\sup \left\{\left\|v-v^{*}\right\|\right\}+1
\end{array}
$$

Let $M:=\max \left\{c_{2} M_{1}, c_{2} M_{1}^{*}, M_{2}, M_{2}^{*}\right\}, \gamma_{0}:=\min \left\{1, \frac{r}{16 M}\right\}$. Then, for $n=1$, by construction $\Phi\left(w^{*}, w_{1}\right) \leq r$. Assume $\Phi\left(w^{*}, w_{n}\right) \leq r$, for some $n \geq 1$, i.e., $\phi\left(u^{*}, u_{n}\right)+$ $\phi\left(v^{*}, v_{n}\right) \leq r$, for some $n \geq 1$. We show that $\Phi\left(w^{*}, w_{n+1}\right) \leq r$. For contradiction, suppose $r<\Phi\left(w^{*}, w_{n+1}\right)$. Observe that $\left\|u_{n+1}-u_{n}\right\|=\| J^{-1}\left(J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right)-$ $J^{-1}\left(J u_{n}\right) \|$. Now, using Lemma 2.4 and recurrence relation (3.14), we have

$$
\begin{aligned}
(2 L)^{-1} \delta_{E}\left(c_{2}^{-1}\left\|u_{n+1}-u_{n}\right\|\right) & \leq\left\langle J u_{n+1}-J u_{n}, u_{n+1}-u_{n}\right\rangle \\
& \leq\left\|J u_{n+1}-J u_{n}\right\|\left\|u_{n+1}-u_{n}\right\| \leq \alpha_{n} M_{1}\left\|u_{n+1}-u_{n}\right\| .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\left\|u_{n+1}-u_{n}\right\| \leq c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right), \text { for some } M_{0}>0 \tag{3.16}
\end{equation*}
$$

Similarly, using Lemma 2.4 and recurrence relation (3.15), we obtain

$$
\begin{equation*}
\left\|v_{n+1}-v_{n}\right\| \leq c_{2} \delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right), \text { for some } M_{0}^{*}>0 \tag{3.17}
\end{equation*}
$$

Now, using recurrence relation (3.14), Lemma 2.1, and inequality (3.16), we have

$$
\begin{align*}
\phi\left(u^{*}, u_{n+1}\right)= & V\left(u^{*}, J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right) \\
\leq & V\left(u^{*}, J u_{n}\right)-2\left\langle u_{n+1}-u^{*}, \alpha_{n}\left(F u_{n}-v_{n}\right)+\alpha_{n} \theta_{n} J u_{n}\right\rangle  \tag{3.18}\\
= & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle \\
& -2 \alpha_{n}\left\langle u_{n+1}-u_{n}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle \\
\leq & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle \\
& +2 \alpha_{n}\left\|u_{n+1}-u_{n}\right\|\left\|F u_{n}-v_{n}+\theta_{n} J u_{n}\right\| \\
\leq & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle+2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right) .
\end{align*}
$$

Observe that by monotonicity of $F$ and the fact that $v^{*}=F u^{*}$, we have $\left\langle u_{n}-u^{*}, F u_{n}-\right.$ $\left.v_{n}+\theta_{n} J u_{n}\right\rangle \geq\left\langle u_{n}-u^{*}, v^{*}-v_{n}+\theta_{n} J u_{n}\right\rangle$. Thus, substituting this in inequality (3.18), we have

$$
\begin{align*}
\phi\left(u^{*}, u_{n+1}\right) \leq & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, v^{*}-v_{n}+\theta_{n} J u_{n}\right\rangle+2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right) \\
= & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, v^{*}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n}-u^{*}, J u_{n}-J u_{n+1}\right\rangle \\
& -2 \alpha_{n} \theta_{n}\left\langle u_{n}-u^{*}, J u_{n+1}\right\rangle+2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right) \tag{3.19}
\end{align*}
$$

Using Lemma 2.2, we have $-2 \alpha_{n} \theta_{n}\left\langle u_{n}-u^{*}, J u_{n+1}\right\rangle \leq \alpha_{n} \theta_{n}\left\|u^{*}\right\|^{2}-\alpha_{n} \theta_{n} \phi\left(u^{*}, u_{n+1}\right)$. Substituting this in inequality (3.19), we obtain

$$
\begin{align*}
\phi\left(u^{*}, u_{n+1}\right) \leq & \phi\left(u^{*}, u_{n}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, v^{*}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n}-u^{*}, J u_{n}-J u_{n+1}\right\rangle \\
(3.20) & +\alpha_{n} \theta_{n}\left\|u^{*}\right\|^{2}-\alpha_{n} \theta_{n} \phi\left(u^{*}, u_{n+1}\right)+2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)  \tag{3.20}\\
\leq & \phi\left(u^{*}, u_{n}\right)-\alpha_{n} \theta_{n} \phi\left(u^{*}, u_{n+1}\right)+\alpha_{n} \theta_{n}\left\|u^{*}\right\|^{2}+2 \alpha_{n} \theta_{n}\left\|u_{n}-u^{*}\right\|\left\|J u_{n}-J u_{n+1}\right\| \\
& +2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, v^{*}-v_{n}\right\rangle \\
\leq & \phi\left(u^{*}, u_{n}\right)-\alpha_{n} \theta_{n} \phi\left(u^{*}, u_{n+1}\right)+\alpha_{n} \theta_{n}\left\|u^{*}\right\|^{2}+2 \alpha_{n} \theta_{n} M_{2}\left(\alpha_{n} M_{1}\right) \\
& +2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)-2 \alpha_{n}\left\langle u_{n}-u^{*}, v^{*}-v_{n}\right\rangle .
\end{align*}
$$

Similarly, using recurrence relation (3.15), Lemma 2.1, inequality (3.17), monotonicity of $K$, the fact that $K v^{*}=-u^{*}$ and Lemma 2.2, we obtain

$$
\begin{align*}
\phi\left(v^{*}, v_{n+1}\right) \leq & \phi\left(v^{*}, v_{n}\right)-\alpha_{n} \theta_{n} \phi\left(v^{*}, v_{n+1}\right)+\alpha_{n} \theta_{n}\left\|v^{*}\right\|^{2}+2 \alpha_{n} \theta_{n} M_{2}^{*}\left(\alpha_{n} M_{1}^{*}\right) \\
& +2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}^{*}\right)-2 \alpha_{n}\left\langle v_{n}-v^{*}, u_{n}-u^{*}\right\rangle . \tag{3.21}
\end{align*}
$$

Thus, adding inequalities (3.20) and (3.21), we obtain

$$
\begin{aligned}
r<\Phi\left(w^{*}, w_{n+1}\right)= & \phi\left(u^{*}, u_{n+1}\right)+\phi\left(v^{*}, v_{n+1}\right) \\
\leq & \Phi\left(w^{*}, w_{n}\right)-\alpha_{n} \theta_{n} \Phi\left(w^{*}, w_{n+1}\right)+\alpha_{n} \theta_{n}\left\|w^{*}\right\|_{W}^{2}+2 \alpha_{n} \theta_{n} M_{2}\left(\alpha_{n} M_{1}\right) \\
& +2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)+2 \alpha_{n} \theta_{n} M_{2}^{*}\left(\alpha_{n} M_{1}^{*}\right)+2 \alpha_{n} c_{2} M_{1} \delta_{E}^{-1}\left(\alpha_{n} M_{0}^{*}\right) \\
\leq & \Phi\left(w^{*}, w_{n}\right)-\alpha_{n} \theta_{n} \Phi\left(w^{*}, w_{n+1}\right)+\alpha_{n} \theta_{n}\left\|w^{*}\right\|_{W}^{2}+2 \alpha_{n} \theta_{n}^{2} M_{2} \gamma_{0} \\
& +2 \alpha_{n} \theta_{n} \gamma_{0} c_{2} M_{1}+2 \alpha_{n} \theta_{n}^{2} M_{2}^{*} \gamma_{0}+2 \alpha_{n} \theta_{n} \gamma_{0} c_{2} M_{1}^{*} \\
\leq & \Phi\left(w^{*}, w_{n}\right)-\alpha_{n} \theta_{n} \Phi\left(w^{*}, w_{n+1}\right)+\alpha_{n} \theta_{n}\left\|w^{*}\right\|_{W}^{2}+2 \alpha_{n} \theta_{n} M \gamma_{0} \\
& +2 \alpha_{n} \theta_{n} M \gamma_{0}+2 \alpha_{n} \theta_{n} M \gamma_{0}+2 \alpha_{n} \theta_{n} M \gamma_{0} \\
\leq & r-\alpha_{n} \theta_{n} r+\frac{3}{4} \alpha_{n} \theta_{n} r=r-\frac{1}{4} \alpha_{n} \theta_{n} r<r .
\end{aligned}
$$

This is a contradiction. Hence, $\Phi\left(w^{*}, w_{n+1}\right) \leq r$. Thus, $\Phi\left(w^{*}, w_{n}\right) \leq r$, for all $n \geq 1$. Consequently, we have $\phi\left(u^{*}, u_{n}\right) \leq r$ and $\phi\left(v^{*}, v_{n}\right) \leq r$, for all $n \geq 1$. Therefore, using inequality (2.6), we deduce that $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ are bounded.

In Theorem 3.5 below, $\left\{\alpha_{n}\right\}$ and $\left\{\theta_{n}\right\}$ are sequences in $(0,1)$ satisfying the following conditions:
(i) $\sum_{n=1}^{\infty} \alpha_{n} \theta_{n}=\infty$,
(ii) $\delta_{E}^{-1}\left(\alpha_{n} M_{0}\right) \leq \theta_{n}^{2} \gamma_{0}$,
(iii) $\delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right) \leq \theta_{n}^{2} \gamma_{0}$,
(iv) $\delta_{E}^{-1}\left(\eta_{n}\right) \rightarrow 0 ; \delta_{E^{*}}^{-1}\left(\eta_{n}\right) \rightarrow 0$,
$(v) \frac{\delta_{E}^{-1}\left(\eta_{n}\right)}{\alpha_{n} \theta_{n}} \rightarrow 0 ; \frac{\delta_{E^{*}}^{-1}\left(\eta_{n}\right)}{\alpha_{n} \theta_{n}} \rightarrow 0$,
where $\eta_{n}=\left(\frac{\theta_{n-1}-\theta_{n}}{\theta_{n}} D\right)$.
We now prove our main Theorem.
Theorem 3.5. Let $E$ be a uniformly convex and uniformly smooth real Banach space. Let $F$ : $E \rightarrow E^{*}, K: E^{*} \rightarrow E$ be maximal monotone mappings. For $u_{1} \in E, v_{1} \in E^{*}$, define the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ in $E$ and $E^{*}$, respectively by

$$
\begin{align*}
& u_{n+1}=J^{-1}\left(J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right)  \tag{3.22}\\
& v_{n+1}=J\left(J^{-1} v_{n}-\alpha_{n}\left(K v_{n}+u_{n}\right)-\alpha_{n} \theta_{n} J^{-1} v_{n}\right),
\end{align*}
$$

where $\left\{\alpha_{n}\right\}$ and $\left\{\beta_{n}\right\}$ are sequences in $(0,1)$ satisfying conditions $(i)-(v)$. Assume that the equation $u+K F u=0$ has a solution. Then, the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ converge strongly to $u^{*}$ and $v^{*}$, respectively, where $u^{*}$ is a solution of $u+K F u=0$ with $v^{*}=F u^{*}$.

Proof. Using Lemmas 2.1 and 2.3, we have

$$
\begin{align*}
\phi\left(y_{n}, u_{n+1}\right)= & V\left(y_{n}, J u_{n}-\alpha_{n}\left(F u_{n}-v_{n}\right)-\alpha_{n} \theta_{n} J u_{n}\right)  \tag{3.23}\\
\leq & V\left(y_{n}, J u_{n}\right)-2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle \\
= & \phi\left(u_{n}, y_{n}\right)-2\left\langle u_{n}+y_{n}, J u_{n}-J y_{n}\right\rangle+2\left(\left\|u_{n}\right\|^{2}-\left\|y_{n}\right\|^{2}\right) \\
& -2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle
\end{align*}
$$

Observe that

$$
\begin{aligned}
\phi\left(u_{n}, y_{n}\right) & =V\left(u_{n}, J y_{n}\right)=V\left(u_{n}, J y_{n-1}+J y_{n}-J y_{n-1}\right) \\
& \leq V\left(u_{n}, J y_{n-1}\right)-2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle .
\end{aligned}
$$

Thus, substituting this in inequality (3.23), and using Lemmas 2.3 and 2.2 we obtain

$$
\begin{align*}
\phi\left(y_{n}, u_{n+1}\right) \leq & V\left(u_{n}, J y_{n-1}\right)-2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle-2\left\langle u_{n}+y_{n}, J u_{n}-J y_{n}\right\rangle \\
(3.24) & +2\left(\left\|u_{n}\right\|^{2}-\left\|y_{n}\right\|^{2}\right)-2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}+\theta_{n} J u_{n}\right\rangle  \tag{3.24}\\
= & \phi\left(y_{n-1}, u_{n}\right)+2\left\langle y_{n-1}+u_{n}, J u_{n}-J y_{n-1}\right\rangle+2\left(\left\|y_{n-1}\right\|^{2}-\left\|y_{n}\right\|^{2}\right) \\
& -2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle-2\left\langle u_{n}+y_{n}, J u_{n}-J y_{n}\right\rangle \\
& -2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n+1}-u_{n}, J u_{n}\right\rangle \\
& -2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n-1}, J u_{n}-J y_{n-1}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n-1}, J y_{n-1}\right\rangle \\
& -2 \alpha_{n} \theta_{n}\left\langle y_{n-1}-y_{n}, J u_{n}\right\rangle \\
\leq & \phi\left(y_{n-1}, u_{n}\right)+2\left\langle y_{n-1}+u_{n}, J u_{n}-J y_{n-1}\right\rangle+2\left(\left\|y_{n-1}\right\|^{2}-\left\|y_{n}\right\|^{2}\right) \\
& -2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle-2\left\langle u_{n}+y_{n}, J u_{n}-J y_{n}\right\rangle \\
& -2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n+1}-u_{n}, J u_{n}\right\rangle \\
& -\alpha_{n} \theta_{n} \phi\left(y_{n-1}, u_{n}\right)-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n-1}, J y_{n-1}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n-1}-y_{n}, J u_{n}\right\rangle \\
= & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}, u_{n}\right)+2\left(\left\|y_{n-1}\right\|^{2}-\left\|y_{n}\right\|^{2}\right)+2\left\langle y_{n-1}-y_{n}, J u_{n}-J y_{n-1}\right\rangle \\
& -2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle-2\left\langle u_{n}+y_{n}, J y_{n-1}-J y_{n}\right\rangle \\
- & 2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n+1}-u_{n}, J u_{n}\right\rangle \\
- & 2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n-1}, J y_{n-1}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n-1}-y_{n}, J u_{n}\right\rangle
\end{align*}
$$

We now estimate the underlined terms. Using equation (2.12) and the fact that $F$ is monotone, we obtain

$$
\begin{aligned}
&-2 \alpha_{n}\left\langle u_{n+1}-y_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n-1}, J y_{n-1}\right\rangle \\
&=-2 \alpha_{n}\left\langle u_{n+1}-u_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n}\left\langle u_{n}-y_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n}-y_{n-1}, J y_{n-1}\right\rangle \\
& \quad-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n}, J y_{n-1}-J y_{n}\right\rangle+2 \alpha_{n}\left\langle u_{n}-y_{n}, F y_{n}-y_{n}^{*}\right\rangle \\
& \leq-2 \alpha_{n}\left\langle u_{n+1}-u_{n}, F u_{n}-v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n}-y_{n-1}, J y_{n-1}\right\rangle \\
& \quad-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n}, J y_{n-1}-J y_{n}\right\rangle+2 \alpha_{n}\left\langle u_{n}-y_{n}, v_{n}-y_{n}^{*}\right\rangle .
\end{aligned}
$$

Thus, substituting this in inequality (3.24), and using inequalities (2.9), (2.10) and (3.16), we obtain

$$
\begin{align*}
\phi\left(y_{n}, u_{n+1}\right) \leq & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}, u_{n}\right)+2\left(\left\|y_{n-1}\right\|^{2}-\left\|y_{n}\right\|^{2}\right)+2\left\langle y_{n-1}-y_{n}, J u_{n}-J y_{n-1}\right\rangle \\
(3.25) & -2\left\langle y_{n}-u_{n}, J y_{n-1}-J y_{n}\right\rangle-2\left\langle u_{n}+y_{n}, J y_{n-1}-J y_{n}\right\rangle  \tag{3.25}\\
& -2 \alpha_{n} \theta_{n}\left\langle u_{n+1}-u_{n}, J u_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n-1}-y_{n}, J u_{n}\right\rangle \\
& -2 \alpha_{n} \theta_{n}\left\langle y_{n}-y_{n-1}, J y_{n-1}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle u_{n}-y_{n}, J y_{n-1}-J y_{n}\right\rangle \\
& -2 \alpha_{n}\left\langle u_{n+1}-u_{n}, F u_{n}-v_{n}\right\rangle+2 \alpha_{n}\left\langle u_{n}-y_{n}, v_{n}-y_{n}^{*}\right\rangle \\
\leq & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}, u_{n}\right)+2 N_{1}\left(\left\|y_{n-1}-y_{n}\right\|+\left\|J y_{n-1}-J y_{n}\right\|\right) \\
& +2 \alpha_{n} \theta_{n} N_{2}\left(\left\|u_{n+1}-u_{n}\right\|+\left\|y_{n-1}-y_{n}\right\|+\left\|J y_{n-1}-J y_{n}\right\|\right) \\
& +2 \alpha_{n} N_{3}\left\|u_{n+1}-u_{n}\right\|+2 \alpha_{n}\left\langle u_{n}-y_{n}, v_{n}-y_{n}^{*}\right\rangle
\end{align*}
$$

$$
\begin{aligned}
\leq & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}, u_{n}\right)+2 N_{1}\left(c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)\right)+2 \alpha_{n} \theta_{n} N_{2}\left(c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)\right. \\
& \left.+c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)\right)+2 \alpha_{n} N_{3} c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)+2 \alpha_{n}\left\langle u_{n}-y_{n}, v_{n}-y_{n}^{*}\right\rangle \\
\leq & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}, u_{n}\right)+\alpha_{n} \theta_{n} \hat{N}\left(c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)+c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)\right. \\
& \left.+\theta_{n} c_{2} \gamma_{0}+c_{2} \delta_{E}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)\right)+2 \alpha_{n}\left\langle u_{n}-y_{n}, v_{n}-y_{n}^{*}\right\rangle,
\end{aligned}
$$

for some $N_{1}, N_{2}, N_{3}>0$, and $\widehat{N}=\max \left\{N_{1}, N_{2}, N_{3}\right\}$. Similarly, using Lemmas 2.1, 2.3 and 2.2, equation (2.13), we obtain

$$
\begin{aligned}
& \phi\left(y_{n}^{*}, v_{n+1}\right) \leq\left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}^{*}, v_{n}\right)+2\left(\left\|y_{n-1}^{*}\right\|^{2}-\left\|y_{n}^{*}\right\|^{2}\right)+2\left\langle y_{n-1}^{*}-y_{n}^{*}, J^{-1} v_{n}-J^{-1} y_{n-1}\right\rangle \\
& \quad+2\left\langle y_{n}^{*}+v_{n}, J^{-1} y_{n}-J^{-1} y_{n-1}^{*}\right\rangle-2\left\langle y_{n}^{*}-v_{n}, J^{-1} y_{n-1}^{*}-J^{-1} y_{n}^{*}\right\rangle \\
&-2 \alpha_{n} \theta_{n}\left\langle v_{n+1}-v_{n}, J^{-1} v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n-1}^{*}-y_{n}^{*}, J^{-1} v_{n}\right\rangle-2 \alpha_{n} \theta_{n}\left\langle y_{n}^{*}-y_{n-1}^{*}, J^{-1} y_{n-1}^{*}\right\rangle \\
&-2 \alpha_{n} \theta_{n}\left\langle v_{n}-y_{n}^{*}, J^{-1} y_{n-1}-J^{-1} y_{n}^{*}\right\rangle-2 \alpha_{n}\left\langle v_{n+1}-v_{n}, K v_{n}+u_{n}\right\rangle+2 \alpha_{n}\left\langle v_{n}-y_{n}^{*}, y_{n}-u_{n}\right\rangle .
\end{aligned}
$$

Thus, using inequalities (2.9), (2.10) and (3.17), we obtain

$$
\begin{align*}
\phi\left(y_{n}^{*}, v_{n+1}\right) \leq & \left(1-\alpha_{n} \theta_{n}\right) \phi\left(y_{n-1}^{*}, v_{n}\right)+\alpha_{n} \theta_{n} \widehat{N}^{*}\left(c_{2} \delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)+c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)\right. \\
& \left.+\theta_{n} c_{2} \gamma_{0}+c_{2} \delta_{E^{*}}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)+c_{2} \delta_{E}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)\right)+2 \alpha_{n}\left\langle v_{n}-y_{n}^{*}, y_{n}-u_{n}\right\rangle \tag{3.26}
\end{align*}
$$

for some $\widehat{N}^{*}>0$. Let $p_{n}=\left(y_{n}, y_{n}^{*}\right)$, adding inequalities (3.25) and (3.26) we obtain $\Phi\left(p_{n}, w_{n+1}\right) \leq\left(1-\alpha_{n} \theta_{n}\right) \Phi\left(p_{n-1}, w_{n}\right)+\alpha_{n} \theta_{n} N\left(c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)+2 c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)+2 c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)\right.$

$$
\begin{equation*}
\left.+2 \theta_{n} c_{2} \gamma_{0}+2 c_{2} \delta_{E}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)+2 c_{2} \delta_{E^{*}}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right)\right) \tag{3.27}
\end{equation*}
$$

where $N=\max \left\{\widehat{N}, \widehat{N}^{*}\right\}$. Now, setting $a_{n}=\Phi\left(p_{n-1}, w_{n}\right) ; \sigma_{n}=\alpha_{n} \beta_{n} ; c_{n} \equiv 0$ and

$$
\begin{aligned}
b_{n}:= & N\left(c_{2} \delta_{E}^{-1}\left(\alpha_{n} M_{0}\right)+2 c_{2} \delta_{E}^{-1}\left(\eta_{n}\right)+2 c_{2} \delta_{E^{*}}^{-1}\left(\eta_{n}\right)+2 \theta_{n} c_{2} \gamma_{0}+2 c_{2} \delta_{E}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)\right. \\
& \left.+2 c_{2} \delta_{E^{*}}^{-1}\left(\frac{\eta_{n}}{\alpha_{n} \theta_{n}}\right)+c_{2} \delta_{E^{*}}^{-1}\left(\alpha_{n} M_{0}^{*}\right)\right),
\end{aligned}
$$

inequality (3.27) becomes $a_{n+1} \leq\left(1-\sigma_{n}\right) a_{n}+\sigma_{n} b_{n}+c_{n}, n \geq 1$. It follows from Lemma 2.9 that $\Phi\left(p_{n-1}, w_{n}\right) \rightarrow 0$, as $n \rightarrow \infty$. By Lemma 2.8, we have $\left\|w_{n}-p_{n-1}\right\|_{W} \rightarrow 0$. Consequently, $\left\|u_{n}-y_{n-1}\right\| \rightarrow 0$. Furthermore, using Remark 2.3, since $\left[y_{n}, y_{n}^{*}\right] \rightarrow\left[u^{*}, v^{*}\right] \in$ $A^{-1} 0$, we have that $\left\{u_{n}\right\}$ converges to a solution of the Hammerstein equation (1.1) with $v^{*}=F u^{*}$. This completes the proof.

Remark 3.4. Real sequences that satisfy the hypothesis of above theorem are $\alpha_{n}=(n+1)^{-a}$ and $\theta_{n}=(n+1)^{-b}$ with $0<b<a$ and $a+b<1$.

## 4. NUMERICAL ILLUSTRATION

In this section, we present a numerical example to compare the convergence of a sequence generated algorithms (1.3) and (1.2), and our algorithm, algorithm (3.22).

Example 4.1. In Theorems 1.2, 1.1 and 3.5 set $E=\mathbb{R}^{2}, E^{*}=\mathbb{R}^{2}$,

$$
F u=\left(u_{1}+u_{2}+\sin u_{1},-u_{1}+u_{2}+\sin u_{2}\right), \quad K v=\left(v_{1}+v_{2}, v_{1}+v_{2}\right) .
$$

Then, it is easy to see that $F$ and $K$ are monotone and the vector $u^{*}=(0,0)$ is the only solution of the equation $u+K F u=0$. In algorithms (1.3) and (3.22), we take $\alpha_{n}=\lambda_{n}=$ $\frac{1}{(n+1)^{\frac{1}{4}}}, \theta_{n}=\frac{1}{(n+1)^{\frac{1}{5}}}, n=1,2, \cdots$, and in algorithm (1.2), we take $\alpha_{n}=\frac{1}{(n+1)^{\frac{1}{2}}}, \beta_{n}=$ $\frac{1}{(n+1)^{\frac{1}{4}}}, n=1,2, \cdots$, as our parameters. Clearly, these parameters satisfy the hypothesis of Theorems 1.2, 1.1 and 3.5, respectively. Choosing $u_{1}=(1,0), v_{1}=(1,1), n=5000$ and using a tolerance of $10^{-8}$ we obtain the following iterates. And in the graph below, $y$-axis represents the values of $\left\|u_{n+1}-\mathbf{0}\right\|$ while the $x$-axis represents the number of iterations $n$.

| CPU time | Alg. (1.3) <br> 0.43 sec | Alg. (1.2) <br> 0.49 sec | Alg. (3.22) <br> 0.21 sec |
| :---: | :---: | :---: | :---: |
| No. iter. | $\left\\|u_{k+1}\right\\|$ | $\left\\|u_{k+1}\right\\|$ | $\left\\|u_{k+1}\right\\|$ |
| 1 | 1.6817 | 1.4142 | 1.6817 |
| 10 | 1.2912 | 0.1825 | 1.2932 |
| 30 | 0.1811 | 0.1566 | 0.0008 |
| 52 | 0.1656 | 0.1385 | $8.8 \times 10^{-9}$ |
| 5000 | 0.0703 | 0.0465 | - |



Remark 4.5. Observe that in this experiment and with the specified tolerance, the sequence of our iteration process converges after 52 iterations, whereas, after 5,000 iterations the sequences of algorithms (1.3) and (1.2), with this given tolerance, are yet to converge. From the results obtained, Algorithm (3.22) would, perhaps, be preferred to either Algorithm (1.3) or Algorithm (1.2) in any possible application.

Acknowledgements. The authors wish to thank the referees for their esteemed comments and suggestions.

## References

[1] Alber, Y. and Ryazantseva, I., Nonlinear Ill Posed Problems of Monotone Type, Springer, London, UK, (2006)
[2] Berinde, V., Iterative Approximation of Fixed points, Lecture Notes in Mathematics, Springer, London, UK, (2007)
[3] Browder, F. E., Nonlinear mappings of nonexpansive and accretive-type in Banach spaces, Bull. Amer. Math. Soc., 73 (1967), 875-882
[4] Brezis, H. and Browder, F. E., Some new results about Hammerstein equations, Bull. Amer. Math. Soc., 80 (1974), 567-572
[5] Brezis, H. and Browder, F. E., Existence theorems for nonlinear integral equations of Hammerstein type, Bull. Amer. Math. Soc., 81 (1975), 73-78
[6] Brezis, H. and Browder, F. E., Nonlinear integral equations and system of Hammerstein type, Advances in Math., 18 (1975), 115-147
[7] Browder, F. E. and Gupta, P., Monotone operators and nonlinear integral equations of Hammerstein type, Bull. Amer. Math. Soc., 75 (1969), 1347-1353
[8] Chepanovich, R. S., Nonlinear Hammerstein equations and fixed points, Publ. Inst. Math. (Beograd) N. S., 35 (1984), 119-123
[9] Chidume, C. E., Geometric Properties of Banach Spaces and Nonlinear iterations, vol. 1965 of Lectures Notes in Mathematics, Springer, London, UK, (2009)
[10] Chidume, C. E. and Shehu, Y., Iterative approximation of solutions of equations of Hammerstein type in certain Banach spaces, Appl. Math. Comput., 219 (2013), 5657-5667
[11] Chidume, C. E. and Shehu, Y., Approximation of solutions of generalized equations of Hammerstein type, Comput. Math. Appl.,63 (2012), 966-974
[12] Chidume, C. E. and Ofoedu, E. U., Solution of nonlinear integral equations of Hammerstein type, Nonlinear Anal., 74 (2011), 4293-4299
[13] Chidume, C. E. and Zegeye, H., Approximation of solutions nonlinear equations of Hammerstein type in Hilbert space, Proc. Amer. Math. Soc., 133 (2005), 851-858
[14] Chidume, C. E. and Zegeye, H., Iterative approximation of solutions of nonlinear equation of Hammerstein-type, Abstr. Appl. Anal., 6 (2003), 353--367
[15] Chidume, C. E. and Zegeye, H., Approximation os solutions of nonlinear equations of monotone and Hammersteintype, Appl. Anal., 8282 (2003), No. 8, 747-758
[16] Chidume, C. E. and Idu, K. O., Approximation of zeros of bounded maximal monotone maps, solutions of Hammerstein integral equations and convex minimization problems, Fixed Point Theory Appl., (2016), DOI: 10.1186/s13663-016-0582-8
[17] Chidume, C. E., Adamu, A. and Chinwendu, L. O., A Krasnoselskii-type algorithm for approximating solutions of variational inequality Problems and Convex Feasibility Problems, J. Nonlinear Var. Anal., 2, No. 2, 203-218
[18] Chidume, C. E., Chinwendu, L. O. and Adamu, A., A Hybrid Algorithm for Approximating Solutions of a Variational Inequality Problem and a Convex Feasibility Problem, Adv. Nonlinear Var. Inequal., 21 (2018), No. 1, 46-64
[19] Chidume, C. E. and Bello, A. U., An iterative algorithm for approximating solutions of Hammerstein equations with monotone maps in Banach spaces, Appl. Math. Comput., 313 (2017), 408--417
[20] Chidume, C. E. and Shehu, Y., Approximation of solutions of equations Hammerstein type in Hilbert spaces, Fixed Point Theory, 16 (2015), No. 1, 91-102
[21] Chidume, C. E. and Djitte, N., An iterative method for solving nonlinear integral equations of Hammerstein type, Appl. Math. Comput., 219 (2013), 5613--5621
[22] Chidume, C. E. and Djitte, N., Iterative approximation of solutions of nonlinear equations of Hammerstein-type, Nonlinear Anal., 70 (2009) 4086--4092
[23] Cioranescu, I., Geometry of Banach spaces, Duality Mapping and nonlinear problems, Kluwer Academic Publishers, Amsterdam, 1990
[24] De Figueiredo, D. G. and Gupta, C. P., On the variational methods for the existence of solutions to nonlinear equations of Hammerstein type, Bull. Amer. Math. Soc., 40 (1973), 470-476
[25] Dolezale, V., Monotone Operators and its Applications in Automation and Network Theory, Studies in Automation and Control, (Elesevier Science Publ.) New York, 1979
[26] Djitte, N. and Sene, M., An iterative Algorithm for Approximating Solutions of Hammerstein Integral Equations, Numerical Functional Analysis and Optimization,Numer. Funct. Anal. Optim., 34 (2013), No. 12, 1299-1316
[27] Goebel, K. and Reich, S., Uniform convexity, hyperbolic geometry, and nonexpansive mappings, Monographs and Textbooks in Pure and Applied Mathematics, vol. 83, Marcel Dekker, inc., New York, 1984
[28] Hammerstein, A., Nichtlineare integralgleichungen nebst anwendungen, Acta Math., 54 (1930), 117-176
[29] Kamimura S. and Takahashi, W., Strong convergence of a proximal-type algorithm in a Banach space, SIAM J. Optim., 13 (2002), 938-945
[30] Kato, T., Nonlinear semigroups and evolution equations, J. Math. Soc. Japan, 19 (1967), 508-520
[31] Lindenstrauss, J. and Tzafriri, L., Classical Banach spaces II: Function Spaces, Ergebnisse Math. Grenzgebiete Bd. 97, Springer-Verlag, Berlin, 1979
[32] Minty, G. J., Monotone (nonlinear) operators in hilbert space, Duke Math. J., 29 (1962), No. 4, 341--346
[33] Minjibir, M. S. and Mohammed, I., Iterative algorithms for solutions of Hammerstein integral inclusions, Appl. Math. Comput., 320 (2018), 389-399
[34] Nilsrakoo, W. and Saejung, S., Strong convergence theorems by Halpern-Mann iterations for relatively nonexpansive maps in Banach spaces, Appl. Math. Comput., 217 (2011), 6577-6586
[35] Pascali, D. and Sburlan, S., Nonlinear Mappings of Monotone Type, Editura Academiei, Bucharest, Romania, 1978
[36] Reich, S., Constructive techniques for accretive and monotone operators in "Applied Nonlinear Analysis" Academic Press, New York (1979), 335-345
[37] Shehu, Y., Strong convergence theorem for integral equations of Hammerstein type in Hilbert spaces, Appl. Math. Comput., 231 (2014), 140-147
[38] Xu, H. K., Iterative algorithms for nonlinear operators, J. Lond. Math. Soc., 66 (2002), No. 2, 240-256
[39] Rockafellar, R. T., Local boundedness of nonlinear Monotone operators, Michigan Math. J., 16 (1969), 397-407
[40] Uba, M. O., Bello A. U. and Chidume, C. E., Approximation of solutions of Hammerstein equations with bounded monotone maps in Lebesgue spaces, PanAmer. Math. J., 29 (2019), No. 2, 34-53
[41] Zarantonello, E. H., Solving functional equations by contractive averaging, U.S. Army Mathematics Research Center, Madison, Wisconsin, 1960, Technical Report 160
[42] Zegeye, H., and Molanza, D. M., Hybrid approximation of solutions of integral equations of the Hammerstein type, Arab. J. Math., 2 (2013), 221-232

African University of Science and Technology
Km 10 Airport Road
Galadimawa, Abuja F.C.T, Nigeria
E-mail address: cchidume@aust.edu.ng
E-mail address: aadamu@aust.edu.ng
E-mail address: lokereke@aust.edu.ng


[^0]:    Received: 12.04.2019. In revised form: 10.08.2019. Accepted: 17.08.2019
    2010 Mathematics Subject Classification. 47H09, 47H10, 47J25 47J05, 47J20.
    Key words and phrases. fixed point, maximal monotone, uniformly smooth, uniformly convex, Hammerstein .
    Corresponding author: C. E. Chidume; cchidume@aust.edu.ng

