Fixed point theorems for nonself Bianchini type contractions in Banach spaces endowed with a graph

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ABSTRACT. In this paper we present an extension of fixed point theorem for self mappings on metric spaces endowed with a graph and which satisfies a Bianchini contraction condition. We establish conditions which ensure the existence of fixed point for a non-self Bianchini contractions $T:K\subset X\to X$ that satisfy Rothe's boundary condition $T(\partial K)\subset K$.

1. Introduction

Starting with well-known Banach contraction principle (see its complete from in [19]), many directions have approached to study the existence of fixed points of a map T. We remember that, for a map $T: X \to X$ the set of fixed point is

$$Fix(T) = \{x \in X; Tx = x\},\$$

where X is a nonempty set. Roughly speaking, the existence conditions of fixed points are a set of rules which reflect the relations between the distances from one element to another of the set $\{x,y,Tx,Ty\}$ and some properties of the map T in the space X. In general, (X,d) is a complete metric space, $T:X\to X$ is a self-mapping which has some specific properties. For example:

a) classical Banach contraction condition

$$d(Tx, Ty) \le a \cdot d(x, y)$$
 for all $x, y \in X$;

b) ([45]) Kannan contraction condition

$$d(Tx, Ty) \le b[d(x, Tx), d(y, Ty)]$$
 for all $x, y \in X$;

c) ([24]) Bianchini contraction condition

$$d(Tx, Ty) \le a \cdot \max \{d(x, Tx), d(y, Ty)\}\$$
 for all $x, y \in X$;

d) Rus-Reich contraction condition

$$d(Tx,Ty) \le \alpha \cdot d(x,Tx) + \beta \cdot d(y,Ty) + \gamma d(x,y)$$
 for all $x,y \in X$;

and so on, where $a \in [0,1)$, $b \in [0,\frac{1}{2})$, respectively $\alpha,\beta,\gamma \in [0,1)$ with $\alpha+\beta+\gamma<1$.

In all these existence results, T is a self-mapping. More details can be found in literature, see [19], [32], [73] and reference therein.

The study of non-self mappings started with the paper of J. Caristi, see [30] for details. The assumption that $T:K\to X$ is non-self, i.e., T maps a subset K of X not into itself and there is at least one $x\in K$ such that $Tx\in X\setminus K$, implies some supplementary conditions which must hold on the boundary of subset K. A list of some type of these conditions can be found in [42]. In this paper we choose the Rothe's boundary condition $T(\partial K)\subset K$. There are a few other results related to the existence of fixed points for

Received: 09.03.2018. In revised form: 11.03.2018. Accepted: 18.03.2018

2010 Mathematics Subject Classification. 47H10, 47H08, 47H09.

Key words and phrases. Fixed point theorem, boundary condition, Bianchini contraction.

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non-self maps, remind here two fixed point theorems for non self contractions defined on Banach spaces endowed with a graph established by M. Păcurar in [21], while very recently in [15] was extend these results to non-self Kannan type contractions on Banach spaces endowed with a graph. The study of set of fixed points of mappings defined on Banach space endowed with a graph was initiated by J. Jachymski in [44] and continued by work of F. Bojor [25, 26, 27, 28, 29] and others [1], [33] etc.

The present work is organized in two sections. In the first one we remind a few preliminary notions and results, basically taken from [20], regarding the fixed point results for mappings defined on metric spaces endowed with a graph. In the second section there is an existence result of fixed point for an non-self mapping which satisfies a Bianchini contraction condition and is defined on metric spaces endowed with a graph.

2. METRIC SPACES ENDOWED WITH A GRAPH

Let (X,d) be a metric space and let Δ denote the diagonal of the Cartesian product $X \times X$. Consider now a directed simple graph G = (V(G), E(G)) such that the set of its vertices, V(G), coincides with X and E(G), the set of its edges, contains all loops, i.e., $\Delta \subset E(G)$.

By G^{-1} we denote the *converse graph* of G, i.e., the graph obtained by G by reversing its edges, i.e.,

$$E(G^{-1}) = \{(y, x) \in X \times X : (x, y) \in E(G)\}.$$

If $x,y \in V(G)$ are vertices in the graph G, then a *path* from x to y of length $N \in \mathbb{N}$ is a sequence $\{x_i\}_{i=1}^N$ of N+1 vertices of G such that

$$x_0 = x, x_N = y \text{ and } (x_{i-1}, x_i) \in E(G), i = 1, 2, \dots, N.$$

A graph G is said to be *connected* if there is at least a path between any two vertices. If $\tilde{G} = (X, E(\tilde{G}))$ is the symmetric graph obtained by putting together the vertices of both G and G^{-1} , i.e.,

$$E(\tilde{G}) = E(G) \cup E(G^{-1}),$$

then G is called *weakly connected* if \tilde{G} is connected. If G = (V(G), E(G)) is a graph and $H \subset V(G)$, then the graph (H, E(H)) with $E(H) = E(G) \cap (H \times H)$ is called the *subgraph* of G determined by H. Denote it by G_H .

Definition 2.1. Let (X, d, G) be a Banach space endowed with a simple directed and weakly connected graph G. We say that the property (L) holds if

for any sequence
$$\{x_n\}_{n=1}^{\infty} \subset X$$
 with $x_n \to x$ as $n \to \infty$ and $(x_n, x_{n+1}) \in E(G)$ for all $n \in \mathbb{N}$, there exists a subsequence $\{x_{k_n}\}_{n=1}^{\infty}$ satisfying $(x_{k_n}, x) \in E(G)$, for all $n \in \mathbb{N}$.

A mapping $T:X\to X$ is said to be (well) defined on a metric space endowed with a graph G if it has the property

$$\forall x, y \in X, (x, y) \in E(G) \text{ implies } (Tx, Ty) \in E(G). \tag{2.1}$$

For a non self mapping $T: K \to X$ we shall say that it is (well) defined on the Banach space X endowed with the graph G if it has this property for the subgraph of G induced by K, that is,

$$(x,y) \in E(G)$$
 with $Tx, Ty \in K$ implies $(Tx,Ty) \in E(G) \cap (K \times K)$, (2.2)

for all $x, y \in K$.

According to [44], a mapping $T: X \to X$, which is well defined on a metric space endowed with a graph G, is called a G-contraction if there exists a constant $\alpha \in (0,1)$ such that for all $x,y \in X$ with $(x,y) \in E(G)$ we have

$$d(Tx, Ty) \le \alpha \cdot d(x, y). \tag{2.3}$$

Let X be a Banach space, K a nonempty closed subset of X and $T: K \to X$ a non-self mapping. If $x \in K$ is such that $Tx \notin K$, then we can always choose an $y \in \partial K$ (the boundary of K) such that $y = (1 - \lambda)x + \lambda Tx$ $(0 < \lambda < 1)$, which actually expresses the fact that

$$d(x,Tx) = d(x,y) + d(y,Tx), y \in \partial K = Fr(K), \tag{2.4}$$

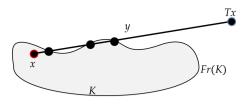


FIGURE 1

where we use the notation

$$d(x,y) = ||x - y||.$$

In general, the set Y of points y satisfying condition (2.4) from above may contain more than one element.

We suppose Y is always nonempty.

In this context we shall need the following important concept first introduced and used in [20].

Definition 2.2. ([20]) Let X be a Banach space, K a nonempty closed subset of X and $T: K \to X$ a non-self mapping. We say that T has property (M) if

Examples of non-self mapping T which has property (M) can be found in work of V. Berinde and M. Păcurar (see [20], [21]) or in the next example.

Example 2.1. Let $K = [0,1] \times [0,1]$ be a subset of $X = \mathbb{R}^2$, where X is endowed with the Chebyshev metric, i.e., $d_{\infty}(x,y) = \max\{|x_1-y_1|, |x_2-y_2|\}$, for all $x = (x_1,x_2)$ and $y = (y_1,y_2)$ in X. Consider the map $T: K \to X$ given by $Tx = T(x_1,x_2) = (-x_1,x_2)$ for all $x = (x_1,x_2) \in K$. Remark that Tx = x for any $x \in \{(0,b): b \in [0,1]\} := K_0$, $K_0 \subset \partial K$ and $Tx \notin K$ for all $x \in K \setminus K_0$. Since

$$d_{\infty}(x,Tx) = 2x_1 \text{ for all } x = (x_1,x_2) \in K$$

and

$$d_{\infty}(y,Ty)=0$$
 for all $y\in K_0$,

we have

$$d_{\infty}(y, Ty) < d_{\infty}(x, Tx)$$

for all $x \in K \setminus K_0$ with $y \in K_0 = Y$. So, T has property (M) and Y is not singleton.

In the next example we can fond another non-self mapping which satisfies some contraction condition and the Rothe's boundary condition, which has the (M) properties and iterations sequence converges to fixed point of it.

Example 2.2. Let $X = \mathbb{R}^2$ endowed with the metric

$$d\left(x,y\right)=\max\left\{|x_1-y_1|,|x_2-y_2|\right\} \text{ for all } x=\left(x_1,x_2\right),y=\left(y_1,y_2\right)\in X$$
 and $K=[-1,1]\times[-1,1]$, i.e.,

$$K = \{x = (x_1, x_2) \in \mathbb{R}^2 : \max\{|x_1|, |x_2|\} \le 1\} \subset X.$$

Let

$$K_1 = \{(x_1, x_2) \in K : 0 > x_2 \ge x_1\}$$

$$K_2 = \{(x_1, x_2) \in K : 0 > x_1 > x_2\}$$
and

$$K_3 = K \setminus (K_1 \cup K_2).$$

Let $T: K \to X$ given by

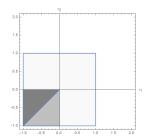
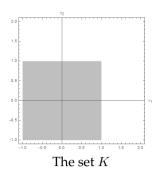


FIGURE 2. The set K and the three subsets K_1 (the gray one), K_2 (the dark one) and K_3 with $K = K_1 \cup K_2 \cup K_3$.

$$Tx = T(x_1, x_2) = \begin{cases} (2x_1 + 2, 2x_2 + 1), & (x_1, x_2) \in K_1 \\ (2x_1 + 1, 2x_2 + 2), & (x_1, x_2) \in K_2 \\ (\alpha x_2, \alpha x_1), & (x_1, x_2) \in K_3 \end{cases}$$
(2.5)

where $\alpha = \frac{1}{2} \in (0,1)$.



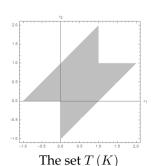


FIGURE 3. The set K and its image by the map T.

Note here some properties of T defined by (2.5).

- **I.** The map T has a unique fix point, $Fix\left(T\right)=\left\{ \left(0,0\right)\right\}$.
- **II.** The Rothe's boundary condition $T(\partial K) \subset K$ holds, where

$$\partial K = \{x = (x_1, x_2) \in \mathbb{R}^2 : \max\{|x_1|, |x_2|\} = 1\}.$$

III. T is a non-self map, i.e., there are $x \in K$ such that $Tx \notin K$. Practically, for every $x = (x_1, x_2) \in K_1$ with $x_1 \in \left(-\frac{1}{2}, 0\right)$ we have $Tx = (2x_1 + 2, 2x_2 + 1)$ with $2x_1 + 2 > 1$, so $Tx \notin K$.

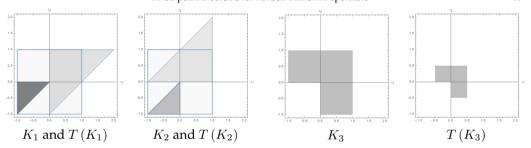


FIGURE 4. The subsets K_1 , K_2 , K_3 of K and their image by the map T.

IV. T has property (M). Indeed, if $x = (x_1, \frac{1}{2}x_1) \in K_1$ with $x_1 \in (-\frac{1}{3}, 0)$, then for any $y = (1, \varepsilon) \in \partial K$ with $\varepsilon \in (-x_1, 1)$ the equality

$$d(x,y) + d(y,Tx) = d(x,Tx)$$
 (2.6)

holds. Much more, if $x=\left(x_1,\frac{1}{2}x_1\right)$ with $x_1\in\left(-\frac{1}{2},-\frac{1}{3}\right)$, then for any $y=(1,\varepsilon)\in\partial K$ with $\varepsilon\in(-x_1,2+3x_1)$ we have $d\left(x,y\right)=1-x_1$, $d\left(x,Tx\right)=2+x_1$ and $d\left(y,Tx\right)=1+2x_1$ for $y=(1,\varepsilon)\in\partial K$. So, the equality (2.6) holds. Hence, T has property (M) and for some x the corresponding set Y is not singleton.

A similar result holds for some specific $x \in K_2$.

V. *T* satisfies a contraction condition.

A) For $x = (x_1, x_2) \in K_1$ and $y = (y_1, y_2) \in K_1$ we have $d(Tx, Ty) = 2 \cdot d(x, y)$, $d(y, Ty) = y_1 + 2$ and

$$d\left(x,Tx\right) = \max\left\{|x_1+2|,|x_2+1|\right\} = \frac{|x_1+2|+|x_2+1|+|x_1+2-x_2-1|}{2} = x_1+2.$$

B) For $x = (x_1, x_2) \in K_2$ and $y = (y_1, y_2) \in K_2$ we have $d(Tx, Ty) = 2 \cdot d(x, y)$, $d(y, Ty) = y_2 + 2$ and

$$d(x,Tx) = \max\{|x_1+1|,|x_2+2|\} = \frac{|x_1+1|+|x_2+2|+|x_1+1-x_1-2|}{2} = x_2+2.$$

VI. Picard iterations of *T*.

On K_3 the map T is a classical contraction and, as we can see in first representation from Figure 5, the sequence of Picard iteration converges.

If the initial point of the Picard iterations is situated in $K_1, x_0 \in K_1$, then there are two possible situations: first one has $Tx_0 \in K_3$ and the sequence of Picard iterations converges and second one has $Tx_0 \notin K$, but we can choose $x_1 \in \partial K \cap K_3$, so Picard iterations converges, too. Such situation is depicted on the left image from Figure 5.

A similar situation can be obtain if we choose the initial point from K_2 , see the right image from Figure 5.

3. FIXED POINT THEOREM FOR NONSELF BIANCHINI TYPE CONTRACTIONS IN BANACH SPACES ENDOWED WITH A GRAPH

In that follow, we establish some conditions which ensure that a nonself Bianchini type contraction has a fixed point in (X, d, G), a Banach space endowed with a simple directed and weakly connected graph.

Let $K \subset X$ a nonempty closed subset of X. We say that $T: K \to X$ is a *Bianchini* contraction if there exists a constant $a \in [0,1)$ such that

$$d(Tx, Ty) \le a \cdot \max\left\{d\left(x, Tx\right), d\left(y, Ty\right)\right\}, \text{ for all } (x, y) \in E(G_K), \tag{3.7}$$

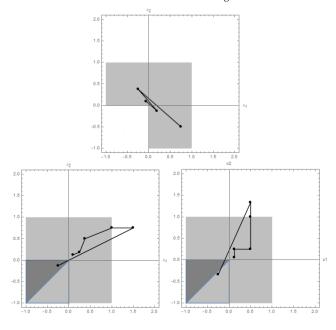


FIGURE 5. Example of Picard iterations.

where G_K is the subgraph of G determined by K.

If T maps K into K, i.e., T is self-mapping, then there are hypotheses which implie that $Fix(T) \neq \emptyset$. Such rezults are Bianchini fixed point theorems [24] with X = K, some theorems establised by F. Bojor [26] and other authors.

The next theorem establishes a fixed point theorem for non-self Bianchini contractions defined on a Banach space endowed with a graph.

Theorem 3.1. Let (X, d, G) be a Banach space endowed with a simple directed and weakly connected graph G such that the property (L) holds. Let K be a nonempty closed subset of X and let $T: K \to X$ be a Bianchini contraction. If $K_T := \{x \in \partial K : (x, Tx) \in E(G)\} \neq \emptyset$, T has property (M) and T satisfies the Rothe's boundary condition $T(\partial K) \subset K$, then

- (i) $Fix(T) = \{x^*\};$
- (ii) Picard iteration $\{x_n = T^n x_0\}_{n=1}^{\infty}$ converges to x^* , for all $x_0 \in K_T$, and the following estimate holds

$$d(x^*, x_n) \le \frac{a^{n-1}}{a-1} \cdot \max \{d(x_0, x_1), d(x_1, x_2)\}, \quad n = 0, 1, 2, \dots$$
(3.8)

Proof. If $T(K) \subset K$, then T is self-mapping and the prove is given by Bianchini fixed point theorem, see [24]. Therefore, we consider only the case $T(K) \cap (X \setminus K) \neq \emptyset$, i.e., there is at least one $x \in K$ such that $Tx \in X \setminus K$. The proof has two parts: first we construct the Picard iteration and establish some properties of this sequence and after that we prove that Picard iteration is a Cauchy sequence.

Let $x_0 \in K_T$. Since $(x_0, Tx_0) \in E(G)$ and T is well defined on a metric space endowed with the graph G, then we have $(T^nx_0, T^{n+1}x_0) \in E(G)$ for all $n \in \mathbb{N}$.

In the following, we construct the Picard iteration $\Xi:=\{x_n\}_{n\geq 1}$. First, we denote $x_1=y_1=Tx_0$ and for $n\geq 2$ we proceed in the following way: if $Tx_{n-1}\in K$ then $x_n=y_n=Tx_{n-1}$, else $Tx_{n-1}\notin K$ and we can choose a $\lambda_n\in (0,1)$ such that

$$x_n = (1 - \lambda_n) x_{n-1} + \lambda_n T x_{n-1} \in \partial K.$$

Now, we can consider two disjoint subsets of the Picard iteration Ξ . One set is

$$P = \{x_k \in \Xi; x_k = y_k = Tx_{k-1}, k \in N_P \subset \mathbb{N}\} \subset K$$

and other one is

$$Q = \{x_k \in \Xi; x_k \neq Tx_{k-1}, k \in N_Q \subset \mathbb{N}\} \subset \partial K.$$

By virtue of Rothe's boundary condition, in Q there is no two consecutive terms of Ξ , but in P we can have consecutive terms of Ξ . So, for a given $n \in \mathbb{N}$ we can have the following three hypothetical cases: (1) $x_n, x_{n+1} \in P$; (2) $x_n \in P$, $x_{n+1} \in Q$ and (3) $x_n \in Q$, $x_{n+1} \in P$.

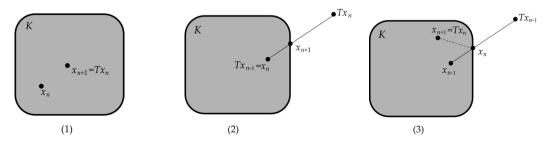


FIGURE 6. The three hypothetical cases:

(1)
$$x_n, x_{n+1} \in P$$
; (2) $x_n \in P$, $x_{n+1} \in Q$; (3) $x_n \in Q$, $x_{n+1} \in P$.

Next, we study the influence of Bianchini condition (3.7) upon the distance between the terms of Ξ in all three cases from above.

Case 1. Assume that $x_n, x_{n+1} \in P$ and

$$\max \{d(x_n, Tx_n), d(x_{n-1}, Tx_{n-1})\} = d(x_n, Tx_n).$$

Since $d(x_n, Tx_n) = d(x_n, x_{n+1}) = d(Tx_{n-1}, Tx_n)$, by (3.7) we have

$$d\left(x_{n},x_{n+1}\right) \leq a \cdot d\left(x_{n},x_{n+1}\right)$$

which implies the inequality

$$(1-a) \cdot d(x_n, x_{n+1}) \le 0$$

and this cannot be hold. So, this situation can not occurs.

Assume that $x_n, x_{n+1} \in P$ and

$$\max\{d(x_n, Tx_n), d(x_{n-1}, Tx_{n-1})\} = d(x_{n-1}, Tx_{n-1}) = d(x_{n-1}, x_n).$$

In this case, $d(Tx_{n-1}, Tx_n) = d(x_n, x_{n+1})$ and (3.7) implies

$$d(x_n, x_{n+1}) \le a \cdot d(x_{n-1}, x_n). \tag{3.9}$$

Case 2. Assume that $x_n \in P$ and $x_{n+1} \in Q$. Hence, there is $\lambda_{n+1} \in (0,1)$ such that

$$x_{n+1} = (1 - \lambda_{n+1}) x_n + \lambda_{n+1} T x_n \in \partial K,$$

which actually express the fact the

$$d(x_n, x_{n+1}) + d(x_{n+1}, Tx_n) = d(x_n, Tx_n).$$

Hence, we have

$$d(x_n, x_{n+1}) = d(x_n, Tx_n) - d(x_{n+1}, Tx_n) \le d(x_n, Tx_n) = d(Tx_{n-1}, Tx_n).$$

Now, by (3.7) we obtain

$$d(x_{n}, x_{n+1}) \leq a \cdot \max \left\{ d(x_{n-1}, Tx_{n-1}), d(x_{n}, Tx_{n}) \right\}$$

$$\leq a \cdot \max \left\{ d(x_{n-1}, x_{n}), d(x_{n}, Tx_{n}) \right\}.$$
(3.10)

If we consider that $\max \{d(x_{n-1}, x_n), d(x_n, Tx_n)\} = d(x_{n-1}, x_n)$, then (3.10) is equivalent to (3.9). On the other hand, if $\max \{d(x_{n-1}, x_n), d(x_n, Tx_n)\} = d(x_n, Tx_n)$ then (3.10) implies

$$d(x_{n}, Tx_{n}) = d(x_{n}, x_{n+1}) \le a \cdot d(x_{n}, Tx_{n}) = a \cdot d(Tx_{n-1}, Tx_{n})$$

$$\le a^{2} \cdot \max \{d(x_{n-1}, Tx_{n-1}), d(x_{n}, Tx_{n})\}$$

$$= a^{2} \cdot d(x_{n}, Tx_{n}).$$

Since $a \in (0,1)$, the last inequality implies $a \cdot d(x_n, Tx_n) < a^2 \cdot d(x_n, Tx_n)$ which is equivalent to

$$a\left(1-a\right) \cdot d\left(x_n, Tx_n\right) < 0$$

and this cannot be hold in our hypotheses.

Case 3. Assume that $x_n \in Q$ and $x_{n+1} \in P$, i.e., $x_n \neq Tx_{n-1} = y_n$, $x_n \in \partial K$ and $x_{n+1} = Tx_n$. In this case, $0 < d(x_{n+1}, x_n) = d(x_n, Tx_n)$ and the property (M) implies

$$d(x_n, Tx_n) \le d(x_{n-1}, Tx_{n-1}) = d(Tx_{n-2}, Tx_{n-1}).$$
(3.11)

Hence, by (3.7) we obtain

$$d(x_{n+1}, x_n) \le a \cdot \max \left\{ d(x_{n-2}, Tx_{n-2}), d(x_{n-1}, Tx_{n-1}) \right\}. \tag{3.12}$$

Now, if we assume that

$$\max \left\{ d\left(x_{n-2}, Tx_{n-2}\right), d\left(x_{n-1}, Tx_{n-1}\right) \right\} = d\left(x_{n-2}, Tx_{n-2}\right) = d\left(x_{n-2}, x_{n-1}\right),$$

then $d(x_n, x_{n+1}) \le a \cdot d(x_{n-2}, x_{n-1})$.

Else, if we consider that

$$\max\left\{d\left(x_{n-2},Tx_{n-2}\right),d\left(x_{n-1},Tx_{n-1}\right)\right\}=d\left(x_{n-1},Tx_{n-1}\right)=d\left(Tx_{n-2},Tx_{n-1}\right),$$

then

$$d(x_{n}, x_{n+1}) \leq a \cdot d(Tx_{n-2}, Tx_{n-1})$$

$$\leq a^{2} \cdot \max\{d(x_{n-2}, Tx_{n-2}), d(x_{n-1}, Tx_{n-1})\}$$

$$= a^{2} \cdot d(x_{n-1}, Tx_{n-1}) = a^{2} \cdot d(Tx_{n-2}, Tx_{n-1}).$$

This implies $d\left(x_{n},x_{n+1}\right)\leq a^{k}\cdot d\left(Tx_{n-2},Tx_{n-1}\right)$ for any $k\in\mathbb{N}$ and this cannot occurs.

At the end of the first part of the proof, we can say that for the elements from the iterative sequence $\Xi = \{x_n\}_{n \geq 0}$ the following inequality holds

$$d(x_n, x_{n+1}) \le a \cdot \max \{d(x_{n-1}, x_n), d(x_{n-2}, x_{n-1})\},$$
(3.13)

for all $n \ge 2$. Now, using consecutively these inequalities (3.13), we obtain

$$d(x_n, x_{n+1}) \le a^{n-1} \cdot \max \{d(x_0, x_1), d(x_1, x_2)\}, n \ge 2.$$
(3.14)

In the second part of this proof, we show that Ξ is Cauchy sequence and T has at least one fixed point. For any $n,p\in\mathbb{N}$ we have

$$d(x_n, x_{n+p}) \le \sum_{k=0}^{p-1} d(x_{n+k}, x_{n+k+1}).$$

Now, by (3.14) we obtain

$$d(x_{n}, x_{n+p}) \leq \sum_{k=0}^{p-1} a^{n+k-1} \cdot \max \left\{ d(x_{0}, x_{1}), d(x_{1}, x_{2}) \right\}$$

$$= \frac{a^{n-1} (1 - a^{p})}{1 - a} \cdot \max \left\{ d(x_{0}, x_{1}), d(x_{1}, x_{2}) \right\}$$

$$< \frac{a^{n-1}}{a - 1} \cdot \max \left\{ d(x_{0}, x_{1}), d(x_{1}, x_{2}) \right\},$$
(3.15)

for any $p \in \mathbb{N}$ and this shows that $\{x_n\}_{n\geq 1}$ is Cauchy sequence in closed set K. So, the sequence $\{x_n\}_{n\geq 1}$ converges to some point x^* in K. By triangle inequality we have

$$d(x^*, Tx^*) \le d(x^*, y) + d(y, Tx^*), y \in K.$$
(3.16)

Property (L) implies there is a subsequence $\{x_{k_n}\}_{n\geq 1}$ of $\{x_n\}_{n\geq 1}$ satisfying

$$(x_{k_n}, x^*) \in E(G)$$
 for all $n \in \mathbb{N}$.

Hence, if we choose $y = x_{k_n+1} = Tx_{k_n}$, then (3.16) implies

$$d(x^*, Tx^*) \le d(x^*, x_{k_n+1}) + d(x_{k_n+1}, Tx^*). \tag{3.17}$$

By Bianchini's type contraction condition (3.7) we have

$$d(x_{k_n+1}, Tx^*) \le a \cdot \max \{d(x_{k_n}, Tx_{k_n}), d(x^*, Tx^*)\}.$$
(3.18)

So, the inequalities (3.17) and (3.18) imply

$$d(x^*, Tx^*) \le d(x^*, x_{k_n+1}) + a \cdot \max \{d(x_{k_n}, Tx_{k_n}), d(x^*, Tx^*)\}.$$

Therefore, we can estimate the distance between x^* and Tx^* by

$$d(x^*, Tx^*) \le \frac{1}{1-a} \cdot d(x^*, x_{k_n+1}) + \frac{a}{1-a} \cdot d(x_{k_n}, Tx_{k_n}) \text{ for all } n \ge 1.$$

and by (3.14) we obtain

$$d(x^*, Tx^*) \le \frac{1}{1-a} \cdot d(x^*, x_{k_n+1}) + \frac{a^n}{1-a} \cdot \max\{d(x_{k_0}, x_{k_1}), d(x_{k_1}, x_{k_2})\}.$$
 (3.19)

Letting now $n \to \infty$ in (3.19), results $d(x^*, Tx^*) = 0$, which shows that x^* is a fixed point of T.

Letting now $p \to \infty$ in (3.15), results the error estimate given by (3.8).

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